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Honeywell Process Solutions

Analog Input Module 2MLF-AV8A, AC8A

User's Guide

ML200-AI R200 September 2010

Release 200

Honeywell

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About This Document

This document describes the procedure to install and configure the 2MLF-AV8A and AC8A; Analog to digital voltage and current converters.

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References

The following list identifies all documents that may be source of reference for material discussed in this publication.

Document Title

SoftMaster User's Guide

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Symbol Definitions

The following table lists the symbols used in this document to denote certain conditions.

Symbol	Definition
	ATTENTION: Identifies information that requires special consideration.
	TIP: Identifies advice or hints for the user, often in terms of performing a task.
	REFERENCE -EXTERNAL: Identifies an additional source of information outside of the bookset.
F	REFERENCE - INTERNAL: Identifies an additional source of information within the bookset.
CAUTION	Indicates a situation which, if not avoided, may result in equipment or work (data) on the system being damaged or lost, or may result in the inability to properly operate the process.
Â	CAUTION : Indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury. It may also be used to alert against unsafe practices.
	CAUTION symbol on the equipment refers the user to the product manual for additional information. The symbol appears next to required information in the manual.
	WARNING : Indicates a potentially hazardous situation, which, if not avoided, could result in serious injury or death.
	WARNING symbol on the equipment refers the user to the product manual for additional information. The symbol appears next to required information in the manual.
4	WARNING, Risk of electrical shock : Potential shock hazard where HAZARDOUS LIVE voltages greater than 30 Vrms, 42.4 Vpeak, or 60 VDC may be accessible.

Symbol Definitions

Symbol	Definition
	ESD HAZARD: Danger of an electro-static discharge to which equipment may be sensitive. Observe precautions for handling electrostatic sensitive devices.
	Protective Earth (PE) terminal : Provided for connection of the protective earth (green or green/yellow) supply system conductor.
Ē	Functional earth terminal : Used for non-safety purposes such as noise immunity improvement. NOTE: This connection shall be bonded to Protective Earth at the source of supply in accordance with national local electrical code requirements.
<u> </u>	Earth Ground : Functional earth connection. NOTE: This connection shall be bonded to Protective Earth at the source of supply in accordance with national and local electrical code requirements.
\rightarrow	Chassis Ground : Identifies a connection to the chassis or frame of the equipment shall be bonded to Protective Earth at the source of supply in accordance with national and local electrical code requirements.

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1. Introduction

1.1 Overview

This user's guide describes two analog input modules.

- 2MLF-AV8A type voltage to digital conversion module
- 2MLF-AC8A type current to digital conversion module.

Both A/D conversion modules are used for converting analog signals (voltage or current input) from PLC's external device to signed 16-bit binary data of digital value. They are used with MasterLogic-200 CPU module, ML200-IEC (2MLI-CPUU), and ML200R (2MLR-CPUH).

1.2 Features

- 1. Module selection: You can choose the module depending on input signal type.
 - a) 2MLF-AV8A: 8 channels, voltage input
 - b) 2MLF-AC8A: 8 channels, current input
- 2. High speed A/D conversion @ 250 µs/channel.
- 3. High conversion accuracy of $\pm 0.2\%$ (ambient temperature of $25 \pm 5^{\circ}$ C).
- 4. High resolution (16-bit) of digital value, that is, 1/16000.
- 5. Simplified module setup/monitoring through GUI:

Setting up an A/D conversion module's operation parameters (that is, range, filter, and so on.) was traditionally a cumbersome process using repetitive sequences of ladder programs. This is now achieved using a user-friendly graphical user interface (GUI) in SoftMaster I/O Parameters. In addition, the A/D conversion value can also be easily monitored using the Special Module Monitoring function.

- 6. Multiple digital output data formats: Fours formats are available, as specified below:
 - a) Unsigned value: $0 \sim +16000$
 - b) Signed value: $8000 \sim + 8000$
 - c) Precise value: Refer to Performance specifications.
 - d) Percentile value: $0 \sim +10000$

1. Introduction

1.2. Features

7. Detecting input signal failure/disconnect: Applicable only when analog input range of $1 \sim 5V$ (or $4 \sim 20$ mA) is used.

1.3 Terminology

Analog value- A

The analog value of the physical measurement is continuously displayed as numerical value. Since the analog value changes continuously, an instantaneous value is given as an input. It could be a measurement of any physical parameter, such as voltage, current, temperature, speed, pressure or flow.



Figure 1 – Analog value

For example, temperature could be changing continuously with respect to time, as shown in Figure 1.



Figure 2 – Example of transducer

Since the changing temperature cannot be directly provide as an input to the A/D converter, it needs to be converted into voltage using a transducer and then provided.

Digital value - D

In a digital electronic circuit, data is processed and saved in the form of numbers 0 and 1 only. The data is processed as a string of 0s and 1s. For example, ON and OFF signals

1. Introduction

1.3. Terminology

can be displayed as 0 and 1, respectively, in a digital system. This is called as the binary numbering system. Decimals stored in binary numbering systems are called binary coded decimals (BCD). Figure 3 displays the digital value of the physical parameter.



Figure 4 – Process in PLC

As the PLC processes only binary numbers, analog values cannot be directly input to the PLC's CPU for calculation. Conversion from analog to digital (as shown in Figure 4) is required. This is done using Analog to Digital converter (A/D conversion module).

Similarly, to get an analog output from a digital value, a Digital to Analog converter (D/A conversion module) is used.

Characteristics of A/D conversion

Voltage input

A/D conversion module is used for converting analog electric signal input from the external device to digital value. Analog input signal converted to digital value can be processed by the PLC's CPU. If analog input range of $-10 \sim 10$ V is used in voltage type of A/D conversion module, -10V of analog input corresponds to output of digital value 0. Analog input of +10V corresponds to output digital value of 16000. This means, an analog input of 1.25mV represents digital value of 1, as shown in Figure 5.



Figure 5 – Characteristics of A/D conversion (voltage input)

Current input

If analog input range of $0 \sim 20$ mA is used in current type of A/D conversion module, the 0mA of analog input corresponds to the output of digital value of 0. Analog input of 20mA corresponds to the output digital value of 16000. This means analog input of 1.25µA represents digital value of 1 (Figure 6).

1. Introduction

1.3. Terminology



Figure 6 – Characteristics of A/D conversion (current input)

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2.1 Performance specifications

Table 1 specifies the performance specifications of A/D conversion modules.

	Specifications				
ltem	2MLF-AV8A (Voltage Input Type)		2MLF-AC8A (Current Input Type)		
	DC 1 ~ 5V				
	DC 0 ~ 5V		DC 4 ~ 20mA	A	
Analog input	DC 0 ~ 10V		DC 0 ~ 20mA		
	DC -10 ~ 10V		(Input Resista	ance 250Ω)	
	(Input Resistance: 1 M Ω n	ninimum)			
Analog input range setting	You can select the analog input range individually for each channel either from user program or through user-friendly GUI I/O parameter function in SoftMaster.				ither from user aster.
	(1) Voltage Type				
	Analog input Digital output	1 ~ 5V	0 ~ 5V	0 ~ 10V	-10 ~ 10V
	Unsigned value	0 ~ 16000			
	Signed value	-8000 ~ 8000			
Digital value	Precise value	1000 ~ 5000	0 ~ 5000	0 ~ 10000	-10000 ~ 10000
	Percentile value	0 ~ 10000			
	(2) Current Type				
	Analog input Digital value	4 ~ 20mA 0 ~ 20mA			
	Unsigned value	0 ~ 16000			

Table 1 – Performance specifications

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2. Specifications 2.1. Performance specifications

lt e ure	Specifications				
item	2MLF-AV8A (Voltag	ge Input Type)	2MLF-AC8A (Current Input Type)		
	Signed value	-8000 ~ 8000	0		
	Precise value	4000 ~ 20000	I	0 ~ 20000	
	Percentile value	0 ~ 10000			
	16-bit binary value	e (data: 14 bits)			
	You can individua user program or th	Ily set the format or rough user-friendly	f digital output o GUI I/O param	data for eac neter functio	h channel either from n in SoftMaster.
	Analog input range	Resolution (1/16000)	Analog i range	nput	Resolution (1/16000)
Maximum	1 ~ 5V	0.250mV	4 a 20m	٨	1.004
resolution	0 ~ 5V	0.3125mV	4~2011	A	1.0μΑ
	0 ~ 10V	0.625mV	0 x 20m	٨	1.25.4
	-10 ~ 10V	1.250mV	0~2011	A	1.25μΑ
Accuracy	$\pm 0.2\%$ or less (when ambient temperature is 25 $\pm 5^{\circ}$ C)				
Accuracy	$\pm 0.3\%$ or less (when ambient temperature is 0 ~ 55°C)				
Maximum conversion speed	250µs/channel				
Absolute maximum input	±15V ±30mA				
Analog input channels	8 channels/ module				
Isolation method	Photo-coupler isolation between input terminal and PLC power (no isolation between channels)				
Terminal connected	18-point terminal				
I/O addresses assigned	Fixed type: 64 points, Variable type: 16 points				

2.1. Performance specifications

Itom	Specifications			
2MLF-AV8A (Voltage Input Ty		2MLF-AC8A (Current Input Type)		
Internal-consumed current	DC 5V: 420mA			
Weight	140g			



ATTENTION

- When A/D conversion module is released from the factory, Offset/Gain value is suitably tuned to work for all input ranges. You cannot modify these values.
- Offset Value: Analog input value when digital output value is 0 with digital output format set to unsigned value.
- Gain Value: Analog input value when digital output value is 16000 with digital output format set to unsigned value.

2.2 Part names and functions

The following example illustrates the parts of 2MLF-AV8A and 2MLF-AC8A modules respectively.



Figure 7 – Parts of 2MLF-AV8A and 2MLF-AC8A

No.	Description
1	RUN LED
	Displays the operation status of 2MLF-AV8A/2MLF-AC8A
	On: Operation normal
	Flickering: Error occurs (For more details, refer to section Error codes)
	Off: DC 5V disconnected, 2MLF-AV8A/2MLF-AC8A module error
2	Terminal
	Analog input terminal, whose respective channels can be connected with external devices.

Table 2 – LED indications

2.3 Characteristics of I/O conversion

Characteristics of I/O conversion is a straight line plotted between the Offset and Gain values when converting analog signal (voltage or current input) from PLC's external device to digital value. I/O conversion characteristics of A/D conversion modules are as follows.



2.3. Characteristics of I/O conversion



I/O characteristics of 2MLF-AV8A

2MLF-AV8A is a module exclusively used for 8-channel analog voltage input. The input range can be set from user program or special module package for respective channels. Output formats of digital data are as specified below:

- Unsigned value
- Signed value
- Precise value
- Percentile value

2.3. Characteristics of I/O conversion

1. If the range is DC $1 \sim 5V$

The digital output value for voltage input characteristics is as specified below:

(Resolution (based on 1/16000): 0.25mV) On the I/O Parameters Setting window, set Input Range to $1 \sim 5V$.

2MLF-AV8A (Voltage, 8-CH)								
Parameter	CH 0	CH 1	CH 2	CH 3	CH 4	CH 5	CH 6	CH 7
🗖 Channel status	Disable							
🔽 Input range	1~5∨	1~5V						
Ou:put type	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000
Filter process	Disable							
Filter constant	1	1	1	1	1	1	1	1
Average setting	Disable							
Average processing	Count-Avr							
Average value	2	2	2	2	2	2	2	2
							ОК	Cancel



Digital output value for voltage input characteristics is as specified below.

Digital output range			Analog	input vol	tage (V)		
Digital output lange	0.952	1	2	3	4	5	5.047
Unsigned value	102	0	4000	8000	12000	16000	16191
(-192 ~ 16191)	-192	0					
Signed value	9102	-8000	-4000	0	4000	8000	8191
(-8192 ~ 8191)	-0192						
Precise value	052	4000	2000	3000	4000	5000	5048
(952 ~ 5048)	902	1000					
Percentile value	120	0	2500	5000	7500	10000	10110
(-120 ~ 10119)	-120	U	2500	5000	7500	10000	10119

(Resolution (based on 1/16000): 0.25mV)

2. If the range is DC $0 \sim 5V$

On the I/O Parameters Setting window, set Input Range to $0 \sim 5V$.

Parameter	CH 0	CH '	CH 2	CH 3	CH 4	CH 5	CH 6	CH 7
🔲 Channel status	Disable	Disatle	Disable	Disable	Disable	Disable	Disable	Disable
🔽 Input range	0~5V	0~5∨	0~5V	0~5∨	0~5V	0~5V	0~5∨	0~5V
Output type	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000
Filter process	Disable	Disatle	Disable	Disable	Disable	Disable	Disable	Disable
Filter constant	1	1	1	1	*	1	1	1
Average setting	Disable	Disatle	Disable	Disable	Disable	Disable	Disable	Disable
Average processing	Count-Avr	Ccunt-Avr						
Average value	2	2	2	2	2	2	2	2



2.3. Characteristics of I/O conversion

Digital output value for voltage input characteristics is as specified below.

Digital output	Analog input voltage (V)									
range	-0.06	0	1.25	2.5	3.75	5	5.05			
Unsigned value	102	0	4000	8000	1200	16000	16101			
(-192 ~ 16191)	-192	0	4000	8000	0	16000	10191			
Signed value	0400	- 8000	-4000	0	4000	8000	8191			
(-8192 ~ 8191)	-0192									
Precise value	60		1250	2500	3750	5000	5060			
(-60 ~ 5060)	-60	0								
Percentile value	120	0	2500	5000	7500	10000	10110			
(-120 ~ 10119)	-120	0	2500	5000	7500	10000	10119			

(Resolution (based on	1/16000): 0.3125mV)
-----------------------	---------------------

If the range is DC $0 \sim 10V$ 3.

Param	eter	CH 0	CH1	CH 2	CH 3	CH 4	CH 5	CH 6	CH 7
🗌 Channe	l status	Disable	Disable	Disable	Disable	Disable	Disable	Disable	Disable
🛛 🗹 Input i	range	0~10V	0~10V	0~10V	0~10V	0~10V	0~10V	0~10V	0~10V
Output	type	016000	016000	016000	016000	C16000	016000	016000	016000
🔲 Filter pi	rocess	Disable	Disable	Disable	Disable	Disable	Disable	Disable	Disable
Filter con	istant	1	1	1	1	1	1	1	1
Average	setting	Disable	Disable	Disable	Disable	Disable	Disable	Disable	Disable
Average pi	rocessing	Count-Avr	Count-Avr	Count-Avr	Count-Avr	Count-Avr	Count-Avr	Count-Avr	Count-Av
Average	value	2	2	2	2	2	2	2	2
								04	Connel
								NU	Lancei
									1
10119	10119	8192	16191	·····					·····
10000	10000	8000	10000 -			+			
						1			
						1			
								/	
7500	7500	4000	12000 -						
7500	7500	4000	12000 — -					/	
7500	7500	4000	12000 — -			 	/		
7500	7500	4000	12000 — -				/		
7500	7500	4000	12000						
7500	7500	4000	12000						
7500	7500	4000	12000 — · 8000 — ·						
7500	7500	4000	12000 — · 8000 — ·						
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7500 5000 2500	7500 5000 2500	4000 0 ~4000	12000 8000 4000						
7500 5000 2500	7500 5000 2500	4000 0 ~4000	12000 8000 4000						
7500 5000 2500	7500 5000 2500	4000 0 -4000	12000 - · 8000 - · 4000 - ·						
7500 5000 2500 0 -120	7500 5000 2500 0 -120	4000 0 -4000 -8000 -8192	12000 8000 4000 - -192 -						
7500 5000 2500 0 -120	7500 5000 2500 0 -120	4000 0 -4000 -8000 -8192	12000 - · 8000 - · 4000 - ·					7	

On the I/O Parameters Setting window, set Input Range to $0 \sim 10$ V.

i.

2.3. Characteristics of I/O conversion

Digital output value for voltage input characteristics is as specified below:

Digital output	Analog input voltage (V)									
range	-0.12	0	2.5	5	7.5	10	10.11			
Unsigned value	102	0	4000	8000	12000	16000	16101			
(-192 ~ 16191)	-192	0	4000	8000	12000	16000	10191			
Signed value	9102	8000	4000	0	4000	8000	0101			
(-8192 ~ 8191)	-0192	-0000	-4000	0	4000	8000	0191			
Precise value	120		0500	5000	7500	10000	10119			
(-60 ~ 5059)	-120	0	2500							
Percentile value	120	0	2500	5000	7500	10000	10110			
(-120 ~ 10119)	-120	U	2500	5000	7500	10000	10119			

(Resolution (based on 1/16000): 0.625mV)

4. If the range is $DC-10 \sim 10V$

On I/O Parameters Setting window, set Input Range to $-10 \sim 10$ V.

Parameter	CH 0	CH 1	CH 2	CH 3	CH 4	CH 5	CH 6	CH 7
🗌 Channel status	Disable							
🔽 Input range	-10~10V							
Ou:put type	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000
Filter process	Disable							
Filter constant	1	1	1	1	1	1	1	1
Average setting	Disable							
Average processing	Count-Avr							
Average value	2	2	2	2	2	2	2	2

2. Specifications 2.3. Characteristics of I/O conversion



Digital output value for voltage input characteristics is as specified below.

Digital output	Analog input voltage (V)										
range	-0.24	-10	-5	0	5	10	10.23				
Unsigned value	-192	0	4000	8000	12000	16000	16101				
(-192 ~ 16191)		0	4000				10191				
Signed value	0400	-8000	-4000	0	4000	8000	8191				
(-8192 ~ 8191)	-0192										
Precise value	10040		2500	5000	7500	10000	10239				
(-10240 ~ 10238)	-10240	U									
Percentile value	100	0	2500	5000	7500	10000	10110				
(-120 ~ 10119)	-120	υ	2500	5000	7500	10000	10119				

(Resolution (based on 1/16000): 1.25mV)

I/O characteristics of 2MLF-AC8A

You can set the current input range through user program or special module package for respective channels. Output formats of digital data are as specified below:

2.3. Characteristics of I/O conversion

- Unsigned value
- Signed value
- Precise value
- Percentile value
- 1. If the range is DC $4 \sim 20$ mA

On I/O Parameters Setting window, set Input Range to 4 ~ 2mA.

Parameter	CH 0	CH 1	CH 2	CH 3	CH 4	CH 5	CH 6	CH 7
🔲 Channel status	Disable							
🔽 Input range	4~20mA							
Output type	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000
Filter process	Disable							
Filter constant	1	1	1	1	1	1	1	1
Average setting	Disable							
Average processing	Count-Avr							
Average value	2	2	2	2	2	2	2	2



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Digital output	Analog input current (mA)									
range	3.808	4	8	12	16	20	20.191			
Unsigned value	102	0	4000	8000	12000	16000	16101			
(-192 ~ 16191)	-192	0	4000	8000	12000	16000	10191			
Signed value	0102	8000	4000	0	4000	8000	9101			
(-8192 ~ 8191)	-0192	-8000	-4000	0	4000	8000	0191			
Precise value	2000	4000	8000	12000	16000	20000	20101			
(3808 ~ 20191)	3808	4000	8000	12000	16000	20000	20191			
Percentile value	120	0	2500	5000	7500	10000	10110			
(-120 ~ 10119)	-120	U	2000	5000	7500	10000	10119			

Digital output value for current input characteristics is as specified below:

(Resolution (based on 1/16000): 1µA)

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2.3. Characteristics of I/O conversion

2. If the range is DC $0 \sim 20$ mA

On the I/O Parameters Setting window, set Input Range to $0 \sim 20$ mA.

		srit, o-umj								
	Parameter		CH 0	CH 1	CH 2	СНЗ	CH 4	CH 5	CH 6	CH 7
	Channel status		Disable	Disable	Disable	Disable	Disable	Disable	Disable	Disable
	🔽 Input range		0~20mA	0~20mA	0~20mA	0~20mA	0~20mA	0~20mA	0~20mA	0~20mA
	Output type		0~16000	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000
	Filter process		Disable	Disable	Disable	Disable	Disable	Disable	Disable	Disable
	Filter constant		1	1	1	1	1	1	1	1
	🗌 Average	setting	Disable	Disable	Disable	Disable	Disable	Disable	Disable	Disable
	Average pr	Average processing Count Av		Count Avr	Count Avr	Count Avr	Count Avr	Count Avr	Count Avr	Count Avr
	Average v	alue	2	2	2	2	2	2	2	2
			_						OK	Cancel
Digital Output Value	10119 10000	20239 20000	8192 8000	16191 16000 — -						
	7500	15000	4000	12000			 			
	5000	10000	0	8000				/		
	2500	5000	-4000	4000						!
alue										
alue	0 -120	0 -240	-8000 -8192	0			¹			
alue	0 -120	0 -240	-8000 -8192	0	0 mA	5 mA	 	nA	15 mA	

Digital output value for current input characteristics is as specified below:

(Resolution (based on 1/16000): 1.25µA)
2.3. Characteristics of I/O conversion

Digital output	Analog input current (mA)								
range	-0.24	0	5	10	15	20	20.23		
Unsigned value	102	0	4000	8000	12000	16000	16101		
(-192 ~ 16191)	-192	0	4000	8000	12000	10000	10191		
Signed value	9102	-8000	-4000	0	4000	8000	8191		
(-8192 ~ 8191)	-0192								
Precise value	240	0	5000	10000	15000	20000	20220		
(3808 ~ 20191)	-240	0	5000	10000	15000	20000	20239		
Percentile value	120	400 0	2500	5000	7500	40000	10110		
(-120 ~ 10119)	-120	U	2000	5000	1000	10000	10119		

CAUTION	1.	If analog input value exceeds the maximum range (For example, 20mA), the digital value is fixed at maximum (For example, 16191 for unsigned) as per above table. Likewise, if analog input value drops below minimum range (For example, 0mA), the digital value is fixed at minimum (For example, -192 for unsigned) as per above table.
	2.	Voltage and current input should not exceed ±15V and ±30mA, respectively. Increase in temperature may lead to erratic reading.
	3.	You cannot modify the Offset/Gain setting for 2MLF-AV8A/AC8A module.

2. Specifications

2.3. Characteristics of I/O conversion

Accuracy

Accuracy of digital output value does not change even if you change the input range. Figure 8 shows the change range of the accuracy at ambient temperature of 25 ± 5 °C with analog input range as $-10 \sim 10V$ and digital output type as unsigned value. $\pm 0.2\%$ at ambient temperature of $25 \pm 5^{\circ}$ C, and $\pm 0.3\%$ at ambient temperature of $0 \sim 55^{\circ}$ C.



Figure 8 – Accuracy

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2.4 Functions

Functions of the input module

Table 3 describes the functions of A/D conversion module.

Table 3 –	Performance	specifications
-----------	-------------	----------------

Function Item	Details
Channel Run/Stop setting	Specify Run/Stop of the channel to execute A/D conversion.
	If the unused channel is set to Stop, the Run time can be reduced.
Input voltage/current range	Specify analog input range to be used.
setting	Four input ranges are available for voltage input module while two input ranges are available for current input module.
Output data format setting	Specify digital output type.
	Four output data formats are provided in this module.
A/D conversion methods	Sampling processing: This is performed if A/D conversion type is not specified.
	Filter processing: This is to introduce delay when there is a noise or sudden change of input value.
	Average processing: Average A/D conversion value based on frequency or time output.
Function to detect input disconnected	The user program detects if an analog input with the range of 1 \sim 5V (4 \sim 20mA) is disconnected.

The following are the three A/D conversion functions.

- Sampling processing
- Filter processing
- Average processing

2. Specifications

2.4. Functions



Sampling process

It collects analog input signal through general A/D conversion processing at specific interval of time. The time required for A/D conversion of analog input signal depends on the number of channels used.

(Processing time) = (Number of Channels used) X (Conversion speed)

Example:

If the number of channels used is 3, its process time is = (3) X $(250\mu s) = 750\mu s$

Sampling is performed to calculate the value of continuous analog signal at a specific interval.

Filter process

Filter process function is used for obtaining stable digital output value by filtering noise or sudden change in input value. Filter constant can be specified for respective channels through user program or I/O parameters setting.

Setting range: $1 \sim 99$ (%)

 $F[n] = (1 - \alpha) \times A[n] + \alpha \times F[n - 1]$

F[n]: Current filter output value

A[n]: Current A/D conversion value

F[n-1]: Previous filter output value

 α : Filter constant (0.01 ~ 0.99: previous value added)

1. If the filter setting value is not specified within $1 \sim 99$, RUN LED blinks at an interval of 1s. In order to set RUN LED to ON status, set the filter setting value within $1 \sim 99$. Then change PLC CPU mode from STOP to RUN. Ensure to clear the request flag (UXY.11.0) from online modification (in RUN mode).

2. If an error occurs in the filter setting value, the default filter setting value 1 is saved.

2MLF-AV8A

- Analog input range: DC $-10 \sim 10V$, digital output range: $0 \sim 16000$.
- If analog input value changes $-10V \sim 10V (0 \sim 16000)$, the filter output value, based on α value, is as specified below.

		Filter O	utput Valı	Pomorko				
α value		1 scan	2 scan	3 scan	Remarks			
*1) 0.01	0	15840	15998	15999	1% inclined toward previous value			
*2) 0.5	0	8000	12000	14000	50% inclined toward previous value			
*3) 0.99	0	160	318	475	99% inclined toward previous value			

*1) 16000 output after about 4 scans

*2) 16000 output after about 22 scans

*3) 16000 output after about 1491 scans (372.75ms for 1 channel Run)

2MLF-AC8A

- Analog input current range: DC $0 \sim 20$ mA, digital output range: $0 \sim 16000$.
- If analog input value changes $0mA \sim 10mA$ ($0 \sim 8000$), the filter output value, based on α value, is as specified below.

		Filter ou	utput valu	Pomarks				
α value		1 scan 2 scan		3 scan	Rendiks			
*1) 0.01	0	7920	7999	7999	1% inclined toward previous value			
*2) 0.5	0	4000	6000	7000	50% inclined toward previous value			
*3) 0.99	0	80	159	237	99% inclined toward previous value			

- *1) 8000 output after about 4 scans
- *2) 8000 output after about 21 scans
- *3) 8000 output after about 1422 scans (355.5ms for 1 channel Run)

If the filter process function is not used, then A/D conversion value is the output. Set the filter value according to the degree of fluctuation of analog input data. If it fluctuates, set a higher filter constant value.

Average process

Average process function is used in A/D conversion to handle abnormal analog input signals. For example, noise, surges, and so on. This process is used to execute A/D conversion of the channel for specified frequency or for specified time, and to save the average of the accumulated sum in the memory. You can define the average processing option and time/frequency value through user program or I/O parameters setting for respective channels.

Average processing type is of time average and count average.

Time average processing

- 1. Setting range: $4 \sim 16000 \text{ (ms)}$
- 2. Average processing count within specified time is decided based on the number of channels used.

Average processing count = $\frac{\text{Setting Time}}{(\text{Number of Channels Used}) \times (\text{Conversion Speed})}$

Example 1:

Channels used: 1, setting time: 16000ms

Average processing count =
$$\frac{16000 \text{ms}}{1 \times 0.25 \text{ms}}$$
 = 64000 times

1 (000

Example 2:

Channels used: 8, setting time: 4ms

Average processing count = $\frac{4ms}{8 \times 0.25ms}$ = 2times

Analog Input Module 2MLF-AV8A, AC8A User's Guide Honeywell

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- a) If the time average value is not specified within 4 ~ 16000, RUN LED blinks at an interval of 1s. In order to set RUN LED to ON status, set the time average value within 4 ~ 16000. Then change PLC CPU mode from STOP to RUN. Ensure to clear the request flag (UXY.11.0) from online modification (in RUN mode).
- b) If an error occurs in set value of time average, the default value of 2 is saved.
- 3. Any remainder produced, when set time is divided by (number of channels used X conversion speed), is ignored. Thus, the average processing frequency is the quotient of [(setting time) ÷ (number of channels used x conversion speed)].

Example:

If the number of channels used is 5 and setting time is 151ms

 $151 \text{ms} \div (5 \text{ X } 0.25 \text{ms}) = 120 \text{times} \dots$ Remainder of 8 is ignored $\rightarrow 120 \text{ times}$

Count average processing

- 1. Setting range: $2 \sim 64000$ (times)
- 2. The time required for average value (frequency average) to be saved on memory, depends on the number of channels used.

Process time = set frequency X number of channels used X conversion speed

- a) If set value of count average is not specified within 2 ~ 64000, RUN LED blinks at an interval of 1s. In order to set RUN LED to On status, reset the set value of frequency average within 2 ~ 64000. Then change PLC CPU mode from STOP to RUN. Ensure to clear the request flag of error clear (UXY.11.0) from online modification (in RUN mode).
- b) If any error occurs in the set value of frequency average, the default value 2 is saved.

Example:

If the number of channels used is 4, and average processing frequency is 50.

50 X 4 X (0.25ms) = 50ms

2. Specifications

2.4. Functions

Function to detect input signal failure/disconnect

1. Input Range

This detection function is available only if the input signal range is $1 \sim 5V$ or $4 \sim 20$ mA. Detection conditions for respective input signal ranges are as described in the below table.

Input signal range	Voltage/Current value regarded as disconnected
1 ~ 5V	0.2V or less
4 ~ 20mA	0.8mA or less

2. Disconnection display for respective channels

Detection status bit of signal failure/disconnect for respective input channels is saved on UXY. 10. (X denotes Base No., and Y denotes Slot No.)

Bit	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Default	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
Assigned	-	-	-	-	-	-	-	-	CH7	CH6	CH5	CH4	CH3	CH2	CH1	CH0

BIT	Description
0	Normal
1	Disconnected

3. Operation

Each bit is set to 1 if an assigned channel is detected as disconnected, and is set back to 0 when the channel is connected back again. In addition, each bit can be used to detect the disconnection in the user program together with execution conditions.

4. Program example

A program example of analog input module installed on Base No. 0 and Slot No. 2 detecting a input signal failure/disconnect and storing the respective channel number on the P area.

(System configuration)

2. Specifications 2.4. Functions

2MLP- ACF2	2MLI- CPUU		2MLF- AV8A	

коооо so //	U02.00,F			K00000 (S)
коооо sз — I —	K0000'	MOV	U02, 10	M0000
	U02,10,0	MOV	0	P0000
	U02,10,1	MOV	1	P0001
	U02.10.2	MOV	2	P0002
	U02,10.3	MOV	3	P0003
	U02,10,4	MOV	4	P0004
	U02.10.5	MOV	5	P0005
	U02,10,6	MOV	6	P0006
	U02.10.7	MOV	7	P0007

2. Specifications 2.4. Functions

3. Installation and wiring

3.1 Installation

Installation environment

The 2MLF-AV8A/AC8A modules have high reliability regardless of their installation environment. The following factors ensure for system reliability and stability.

1. Environmental prerequisites

Avoid installing the module in places where it is subjected or exposed to:

- a) Water leakage and dust
- b) Continuous shocks or vibrations
- c) Direct sunlight
- d) Dew condensation due to rapid temperature change
- e) Temperatures outside the range of 0 to $55 \square C$
- 2. Precautions during installing and wiring
 - a) Ensure that no external materials like wire scraps enter the upper part of the PLC during drilling or wiring..
 - b) Ensure to install PLC in a location where it is easy for monitoring and use.
 - c) Ensure that PLC is not located on the same panel where high voltage equipment is located.
 - d) Ensure that the distance from the walls of duct and external equipment is 50mm or more.
 - e) Ensure that the PLC is properly grounded to locations that have good ambient noise immunity.

3. Installation and wiring

3.1. Installation

Handling precautions

The following precautions must be taken when unpacking and installing the Analog Input Module.

- 1. Do not drop the module, and avoid any strong or sudden shocks.
- 2. Do not remove the PCB from its case. It can result in damage or an abnormal operation.
- 3. Do not install or remove the module to/from the base when the power supply is turned on.

3.2 Wiring

Precautions for wiring

The following precautions must be taken when wiring the Analog Input Module.

- 1. The module must be kept away from the alternating current (A/C) wire to avoid surge or inductive noise produced from the A/C supply wire.
- 2. Select the cable considering the ambient temperature and value of the current. The maximum size of the cable must not be less than the standard cable size of AWG22 (0.3mm²).
- 3. The cable must not be too close to a hot device/material and in direct contact with oil for a long period, as it can result in damage or abnormal operation due to short-circuit.
- 4. The polarity check must be performed before wiring.

Wiring examples

The following figures illustrate a sample wiring of 2MLF-AV8A/AC8A.

2MLF-AV8A

3. Installation and wiring

3.2. Wiring

2MLF-AC8A

- 1. Use a 2-core twisted shielded wire. AWG 22 is recommended for the cable standard.
 - a) 2MLF-AC8A's input resistance is 250Ω (typical).
 - b) 2MLF-AV8A's input resistance is $1M\Omega$ (minimum).
- 2. Enable (Run) only the channels those are used and disable the rest to maintain best overall conversion speed.
- 3. Analog input module does not provide power for the input device. Use an external power supply.

Wiring example of 2-wire sensor/transmitter (current input)

Wiring example of 4- wire sensor/transmitter (voltage/current input)

Relationship between voltage input accuracy and wiring length

With voltage input, the wiring (cable) length between transmitter/sensor and module has an effect on digitally-converted values of the module as specified below:

where,

Rc: Resistance value due to line resistance of cable

Rs: Internal resistance value of transmitter or sensor

Ri: Internal resistance value $(1M\Omega)$ of voltage input module

Vin: Voltage allowed to analog input module

% Vi: Tolerance of converted value (%) due to source and cable length in voltage input

$$Vin = \frac{Ri \times Vs}{\left[Rs + (2 \times Rc) + Ri\right]}$$

% $Vi = \left(1 - \frac{Vin}{Vs}\right) \times 100\%$

ATTENTION

With current input, there is no accuracy, tolerance caused by cable length and internal resistance of the source.

3. Installation and wiring 3.2. Wiring

4. Operating Procedures and Monitoring

4.1 Operating procedures

The following flowchart illustrates the procedure to initialize the operation of the Analog Input Module.

Figure 9 – Operating procedure

4. Operating Procedures and Monitoring

4.2. Run parameters setting

4.2 Run parameters setting

The Run parameters of A/D conversion module can be specified using SoftMaster's I/O parameters.

Setting items

SoftMaster provides a graphical user interface (GUI) for setting the parameters of A/D conversion module. These settings are available as I/O parameters option on the SoftMaster project window.

The following table lists the I/O parameter setting functions..

Item	Details
I/O parameters	Specify the following setting items necessary for the module operation.
	Channel Enable/Disable
	Input Voltage/Current Range
	Output Data Format Setting
	Filter Processing Enable/Disable Setting
	Filter Constant Setting
	Average Processing Enable/Disable Setting
	Average Processing Method Setting
	Average Value Setting
	The above data specified by user through SoftMaster is directly saved on A/D conversion module when Special Module Parameters are downloaded. In other words, the download has no relevance to the CPU status, that is, RUN or STOP.

Setting I/O parameters

The procedure for setting I/O parameters based on 2MLF-AV8A is described as follows: The procedure remains same for 2MLF-AC8A.

Step	Action
1	Run SoftMaster to create a project.
	(Refer to SoftMaster User's Guide for details on how to create the project)
2	On the Project window, double-click I/O Parameters .

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4. Operating Procedures and Monitoring

4.2. Run parameters setting

Step	Action
3	Click the slot on which the A/D conversion module is installed. Here, the 8- channel voltage type of A/D conversion module is installed on Base No. 1, Slot No. 4.
4	Click the arrow button on the Module cell display the list of applicable

5 Click **Details** and specify the parameters for respective channel as below:

Channel Status: This enables or disables the respective channel. Select either Disable or Enable from the drop-down list.

CH 0	CH 1	CH 2	CH 3	CH 4	CH 5	CH 6	CH 7
Disable 🔻	Disable	Disable	Disable	Disable	Disable	Disable	Disable
Disable	1~5V	1~5V	1~5V	1~5V	1~5V	1~5V	1~5V
Enable	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000
Disable	Disable	Disable	Disable	Disable	Disable	Disable	Disable
1	1	1	1	1	1	1	1
Disable	Disable	Disable	Disable	Disable	Disable	Disable	Disable
Count-Avr	Count-Avr	Count-Avr	Count-Avr	Count-Avr	Count-Avr	Count-Avr	Count-Avr
2	2	2	2	2	2	2	2
	CH 0 Disable Enable Disable 1 Disable Count-Avr 2	CH 0 CH 1 Disable V Disable Disable 0-16000 Disable 0-16000 Disable Disable 1 1 Disable Disable Count-Avr Count-Avr 2 2	CH 0 CH 1 CH 2 Disable Disable Disable Disable 0-15000 0-15000 Disable Disable Disable 1 1 1 1 Disable Disable Disable Count-Awr Count-Awr 2 2 2 2	CH 0 CH 1 CH 2 CH 3 Disable Disable Disable Disable Disable I-5V 1-5V 1-5V Disable 0-16000 0-16000 0-16000 Disable Disable Disable Disable Disable Disable Disable Disable Disable Disable Disable Disable Disable Disable Disable Disable QuintAwr CountAwr CountAwr CountAwr	CH 0 CH 1 CH 2 CH 3 CH 4 Disable Disable Disable Disable Disable Disable Disable Disable Disable Disable Disable 1-5V 1-5V 1-5V 1-5V Disable 0-16000 0-16000 0-16000 0-16000 Disable Disable Disable Disable Disable 1 1 1 1 1 Disable Disable Disable Disable Disable 2 2 2 2 2 2	CH 0 CH 1 CH 2 CH 3 CH 4 CH 5 Disable <	CH 0 CH 1 CH 2 CH 3 CH 4 CH 5 CH 6 Disable Disable

Input range: Select the range for analog input voltage (or current) as applicable. 2MLF-AV8A provides four voltage input ranges, and 2MLFAC8A provides two current input ranges.

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`4. Operating Procedures and Monitoring 4.2. Run parameters setting

2MLF-AV8A (Voltage, 8-CH)								
2MLF-AV8A (Voltage, 8-	CH)							
Parameter	CHO	CH 1	CH 2	CH 3	CH 4	CH 5	CH6	CH7
Channel status	Enable	Disable	Disable	Disable	Disable	Disable	Disable	Disable
Input range	1~5V •	1~5V	1~5V	1~5V	1~5V	1~5V	1~5V	1~5V
Output type	1~5V	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000	0~1600
Filter process	0~5∨	Disable	Disable	Disable	Disable	Disable	Disable	Disable
Filter constant	0~10V	1	1	1	1	1	1	1
Average setting	Disable	Disable						
Average processing	Count-Avr	Count-A						
Average value	2	2	2	2	2	2	2	2

4. Operating Procedures and Monitoring

4.2. Run parameters setting

Step

Action

Output type: Select the format of output data from the list of available formats.

Parameter	CH 0	CH1	CH 2	CH 3	CH 4	CH 5	CH 6	CH 7
Channel status	Enable	Disable	Disable	Disable	Disable	Disable	Disable	Disable
Input range	1~5V	1~5V	1~5V	1~5V	1~5V	1~5V	1~5V	1~5V
Output type	0~16000 💌	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000
Filter process	0~16000	Disable	Disable	Disable	Disable	Disable	Disable	Disable
Filter constant	-8000~8000	1	1	1	1	1	1	1
Average setting	1000~5000	Disable	Disable	Disable	Disable	Disable	Disable	Disable
Average processing	Counteraw	Count-Avr	Count-Avr	Count-Avr	Count-Avr	Count-Avr	Count-Avr	Count-Av
Average value	2	2	2	2	2	2	2	2

Filter process: Enable or disable the filter process as necessary.

Parameter	CH 0	CH 1	CH 2	CH 3	CH 4	CH 5	CH6	CH 7
Channel status	Enable	Disable	Disable	Disable	Disable	Disable	Disable	Disable
Input range	1~5V	1~5V						
Output type	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000
Filter process	Disable 🔻	Disable	Disable	Disable	Disable	Disable	Disable	Disable
Filter constant	Disable	1	1	1	1	1	1	1
Average setting	Enable	Disable	Disable	Disable	Disable	Disable	Disable	Disable
Average processing	Count-Avr	Count-Av						
Average value	2	2	2	2	2	2	2	2

Filter constant: This field is active only when the filter process is enabled. Double-click the filter constant to enter the value. The available range is $1\sim99$.

Parameter	CH 0	CH1	CH 2	CH 3	CH 4	CH 5	CH 6	CH 7
Channel status	Enable	Disable	Disable	Disable	Disable	Disable	Disable	Disable
☐ Input range	1~5V	1~5V						
Output type	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000
Filter process	Enable	Disable	Disable	Disable	Disable	Disable	Disable	Disable
Filter constant	99	1	1	1	1	1	1	1
Average setting	Disable	Disable						
Average processing	Count-Avr	Count-A						
Average value	2	2	2	2	2	2	2	2

Average setting: Enable or disable the average process as necessary.

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Step

Action

ILF-AV8A (Voltage, 8-	CH)							
Parameter	CHO	CH 1	CH 2	CH 3	CH 4	CH 5	CH 6	CH 7
Channel status	Enable	Disable						
Input range	1~5V	1~5V	1~5V	1~5V	1~5∀	1~5∀	1~5V	1~5V
Output type	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000
Filter process	Enable	Disable						
Filter constant	99	1	1	1	1	1	1	1
Average setting	Disable 👻	Disable						
Average processing	Disable	Count-Avr						
Average value	Enable	2	2	2	2	2	2	2

Average processing: This field is active only when the average process is enabled. You can select average processing as time average or count average.

Parameter	CHO	CH1	CH 2	CH 3	CH 4	CH 5	CH 6	CH 7
Channel status	Enable	Disable	Disable	Disable	Disable	Disable	Disable	Disable
Input range	1~5V	1~5V	1~5V	1~5V	1~5V	1~5V	1~5V	1~5V
Output type	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000
Filter process	Disable	Disable	Disable	Disable	Disable	Disable	Disable	Disable
Filter constant	1	1	1	1	1	1	1	1
Average setting	Enable	Disable	Disable	Disable	Disable	Disable	Disable	Disable
Average processing	Count-Avr 👻	Count-Avr	Count-Avr	Count-Avr	Count-Avr	Count-Avr	Count-Avr	Count-Av
Average value	Count-Avr	2	2	2	2	2	2	2

Average value: This field is active only when the average process setting is enabled. Double-click the average value to input the value. The available range is $2 \sim 64000$ for count average, and $4 \sim 16000$ for time average.

Parameter	CHO	CH1	CH 2	CH 3	CH 4	CH 5	CH 6	CH 7
Channel status	Enable	Disable	Disable	Disable	Disable	Disable	Disable	Disable
Input range	1~5V	1~5V						
Output type	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000
Filter process	Disable	Disable						
Filter constant	1	1	1	1	1	1	1	1
Average setting	Enable	Disable	Disable	Disable	Disable	Disable	Disable	Disable
Average processing	Count-Avr	Count-Avr	Ccunt-Avr	Count-Avr	Count-Avr	Count-Avr	Count-Avr	Count-Av
Average value	32000	2	2	2	2	2	2	2

Select all channels to change parameters.

- a) Select the check box in the parameters item in order to change the parameters of all channels to identical setting value.
- b) Change the parameters of any one channel to change the parameters of the all channels at a time.

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4. Operating Procedures and Monitoring

4.2. Run parameters setting

Step

Action

Following figure shows an example where the Channel Status of all the channels are enabled at the same time.

Parameter	CHO	CH1	CH 2	CH 3	CH4	CH 5	CH6	CH 7
Channel status	Enable -	Enable						
Input range	1~5V							
Output type	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000
Filter process	Disable							
Filter constant	1	1	1	1	1	1	1	1
Average setting	Enable	Disable						
Average processing	Count-Avr							
Average value	32000	2	2	2	2	2	2	2

4.3 Special module monitoring

The special module monitoring function helps you to monitor the analog input modules for testing. It also helps in tuning parameters like average processing constants.

To monitor and test the module, perform the following steps.

Step	Action
1	Click Online > Connect . The SoftMaster is connected to PLC.
2	Click Monitor> Special Module Monitoring . The Special Module List window appears. This window displays base/slot information in addition to special module type.
	ATTENTION
	If the module status is not Online, the Special Module Monitoring menu is disabled.
3	Click Module Info to display the module information as shown in the following figure.
	Special Module Information Y × Displays the informations of special module. Item Information Module Info 2MLF-AV8A (Voltage, 8-CH) OS Version Module O/S Version 1.10 OS Date 2005/5/9 Module Status No Error. (0) Module Information
	ОК

- 4
 - On the **Special Module List** window, select the module and click **Monitor**. The **Monitor Special Module** window appears.

4. Operating Procedures and Monitoring

4.3. Special module monitoring

Step

Α	C	ti	0	n

Item	Max/Min Value	Current Calue	
CH0 A/D Value			
CH1 A/D Value			
CH2 A/D Value			
CH3 A/D Value			
CH4 A/D Value			
CH5 A/D Value			
CH6 A/D Value		10-0500 0000 0000 0000 0000000	
CH7 A/D Value			
Item	Setting Value	Current Value	
Channels	CH	10	
Channel Status	Disable		
Input Range	1~5V		
Output Type	0~16000		- c1 . 1 1
Filter Process	Disable		Selected chann
Filter Constants	1		
Average Process	Disable		
Average Method	Count-Avr		

The four buttons available are:

- Reset max./min value
- Start Monitoring
- Test
- Close

The current value of A/D conversion output and maximum/minimum value are displayed in upper-half of the monitoring window. Parameter settings for each selected channel are displayed in the lower-half of the monitoring window.

5 Click **Start Monitoring** to display the current values A/D conversion output of all channels.

`4. Operating Procedures and Monitoring 4.3. Special module monitoring

6 Click **Test** to temporarily modify the current parameters of A/D conversion module for testing. Make suitable parameter changes in the lower-half of the window and click **Test** button to execute the changes.

To permanently download new settings to the A/D conversion module, make changes in the **I/O parameters setting** window.

7 Reset Max./Min. value The maximum/minimum value field in the window shows the maximum and minimum value of A/D conversion computed for the current session. Click Reset max./min. value to initialize them. The following figure shows the channel 0's A/D converted value when reset.

Step

4. Operating Procedures and Monitoring 4.3. Special module monitoring

Step

Action

ltem	Max/Min Value	Current Calu
CH0 A/D Value	8000/7999	8000
CH1 A/D Value	0/0	0
CH2 A/D Value	0/0	0
CH3 A/D Value	0/0	0
CH4 A/D Value	0/0	0
CH5 A/D Value	0/0	0
CH6 A/D Value	0/0	0
CH7 A/D Value	0/0	0
Item	Setting Value	Current Valu
Channels	CH	10
Channel Status	Enable	Enable
Input Range	-10~10V	-10~10V
Output Type	0~16000	0~16000
Filter Process	Disable	Disable
Filter Constants	1	1
Average Process	Disable	Disable
Average Method	Count-Avr	Count-Avr
Average Value	2	2
Reset max/min value	Stop Monitoring	Test
N		

8 Click **Close** to close the monitoring/test window.

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4.4 Register special module variables

This section describes the automatic registration function of Special Module Variables in the SoftMaster. In MasterLogic PLCs, examples of Special Modules are Analog I/O Modules, RTD, TC modules, HSC modules, position control modules.

Registering special module variables

Register the variables for each module referring to the special module information set in the I/O parameters. You can modify the variables.

To modify the variables, perform the following steps.

Step	Action					
1	On the Project Window, double-click I/O parameters . The I/O Parameters Setting window appears.					
2	Click the module area of the concerned slot to select the applicable module and select the special module type					
3	Double-click the selected 2MLF-AV8A module or click Details to set parameter.					
4	On the Project Window , double-click Global Variables/Address . The registered global variables are displayed in the right-pane.					
5	To register special module variables automatically in the global variables list, click Edit > Register Special/Communication Module Variables .					
	The following confirmation message appears.					
	SoftMaster					
	Automatically register Special Module Variables in global variables list. The previous list will be deleted. Continue?					

<u>Y</u>es

No

4. Operating Procedures and Monitoring

4.4. Register special module variables

Step

Action

6 Click **Yes**. The registered variables are displayed as shown in the following figure.

Variable Kind	Variable Name	Type	Address	Initial Value	Retain	Used	Comment
1 VAR_GLOBAL	_0202_CH0_ACT	BOOL	%UX2.2.16		Г	Г	Analog Input Module: CH0 Active
2 VAR_GLOBAL	_0202_CH0_DATA	INT	%UW2.2.2		Г	Г	Analog Input Module: CH0 Output
3 VAR_GLOBAL	_0202_CH0_HOOR	BOOL	%UX2.2.320		Г	Г	Analog Input Module: CH0 High Out Of Range
4 VAR_GLOBAL	_0202_CH0_IDD	BOOL	%UX2.2.160		Г	Г	Analog Input Module: CH0 Input Disconnection
5 VAR_GLOBAL	_0202_CH0_LOOR	BOOL	%UX2.2.336		Г	Г	Analog Input Module: CH0 Low Out Of Range
6 VAR_GLOBAL	_0202_CH1_ACT	BOOL	%UX2.2.17		Г	Г	Analog Input Module: CH1 Active
7 VAR_GLOBAL	_0202_CH1_DATA	INT	%UW2.2.3		Г	Г	Analog Input Module: CH1 Output
8 VAR_GLOBAL	_0202_CH1_HOOR	BOOL	%UX2.2.321		Г	Г	Analog Input Module: CH1 High Out Of Range
9 VAR_GLOBAL	_0202_CH1_IDD	BOOL	%UX2.2.161		Г	Г	Analog Input Module: CH1 Input Disconnection
10 VAR_GLOBAL	_0202_CH1_LOOR	BOOL	%UX2.2.337		Г	Г	Analog Input Module: CH0 Low Out Of Range
11 VAR_GLOBAL	_0202_CH2_ACT	BOOL	%UX2.2.18		Г	Г	Analog Input Module: CH2 Active
12 VAR_GLOBAL	_0202_CH2_DATA	INT	%UW2.2.4		Г	Г	Analog Input Module: CH2 Output
13 VAR_GLOBAL	_0202_CH2_HOOR	BOOL	%UX2.2.322		Г	Г	Analog Input Module: CH2 High Out Of Range
14 VAR_GLOBAL	_0202_CH2_IDD	BOOL	%UX2.2.162		Г	Г	Analog Input Module: CH2 Input Disconnection
15 VAR_GLOBAL	_0202_CH2_LOOR	BOOL	%UX2.2.338		Г	Г	Analog Input Module: CH0 Low Out Of Range
16 VAR_GLOBAL	_0202_CH3_ACT	BOOL	%UX2.2.19		Г	Г	Analog Input Module: CH3 Active
17 VAR GLOBAL	0202 CH3 DATA	INIT	%1 hu/2 2 5		F	Г	Analog Input Module: CH3 Output

Saving variables

The variables can be saved as a text file as follows:

• On the Global Variable/Address window, click Edit > Export Variables to File.

Program example with variable and address

The below program shows procedure to read the A/D conversion values when the module is in READY condition and to transfer each of the 8 channels digital value (only when enabled) to D area.

`4. Operating Procedures and Monitoring 4.4. Register special module variables

	U01.00.F			M00010
A	Module: Module Ready			(5)
M00010	M00011	U01.01.0	MOV U01	.02 D00100
	12.1	Analog Input Module: CH0 Active	Analog Mod CH0 (i Input ule:)utput
		U01.01.1	MOV U01	.03 D00101
		Analog Input Module: CH1 Active	Analog Mod CH1 (i Input ule:)utput
		U01.01.2	MOV U01	.04 D00102
		Analog Input Module: CH2 Active	Analog Mod CH2 (i Input ule:)utput
		U01.01.3	MOV U01	.05 D00103
		Analog Input Module: CH3 Active	Analog Mod CH3 (i Input ule:)utput
		U01.01.4	MOV UB1	.06 D00104
		Analog Input Module: CH4 Active	Analog Mod CH4 (i Input ule:)utput
	U01.01.5	MOV U01	.07 D00105	
		Analog Input Module: CH5 Active	Analog Mod CH5 (i Input ule:)utput
		U01.01.6	MOV U01	.08 D00106
		Analog Input Module: CH6 Active	Analo Mod CH6 (i Input ule: Jutput
		U01.01.7	MOV U01	.09 D00107
		Analog Input Module: CH7 Active	Analog Mod CH7 (i Input ule:)utput

Figure 10 – Program example with variables and addresses

4. Operating Procedures and Monitoring 4.4. Register special module variables

5. Configuration and Function of Internal Memory

5.1 Internal memory configuration

A/D conversion module has its own internal memory to transmit/receive data to/from PLC CPU.

The following table lists the details of the I/O area of A/D converted data..

Address Assigned	Global Variable	Details	R/W	Directio n
%UXa.b.0	_ab_ERR	Module ERROR	Б	$A/D \rightarrow$
%UXa.b.15	_ab_RDY	Module READY	ĸ	CPU
%UXa.b.16	_ab_CH0_ACT	CH0 Active		
%UXa.b.17	_ab_CH1_ACT	CH1 Active		
%UXa.b.18	_ab_CH2_ACT	CH2 Active		
%UXa.b.19	_ab_CH3_ACT	CH3 Active	Б	$A/D \rightarrow$
%UXa.b.20	_ab_CH4_ACT	CH4 Active	ĸ	CPU
%UXa.b.21	_ab_CH5_ACT	CH5 Active		
%UXa.b.22	_ab_CH6_ACT	CH6 Active		
%UXa.b.23	_ab_CH7_ACT	CH7 Active		
%UWa.b.2	_ab_CH0_DATA	CH0 Output		
%UWa.b.3	_ab_CH1_DATA	CH1 Output		
%UWa.b.4	_ab_CH2_DATA	CH2 Output		
%UWa.b.5	_ab_CH3_DATA	CH3 Output		A/D → CPU
%UWa.b.6	_ab_CH4_DATA	CH4 Output	ĸ	
%UWa.b.7	_ab_CH5_DATA	CH5 Output		
%UWa.b.8	_ab_CH6_DATA	CH6 Output		
%UWa.b.9	_ab_CH7_DATA	CH7 Output		

Table 5 – I/O area of A/D converted data

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5. Configuration and Function of Internal Memory

5.1. Internal memory col	ntiguration
--------------------------	-------------

Address Assigned	Global Variable	Details	R/W	Directio n
%UXa.b.160	_ab_CH0_IDD	CH0 Input Disconnection		
%UXa.b.161	_ab_CH1_IDD	CH1 Input Disconnection		
%UXa.b.162	_ab_CH2_IDD	CH2 Input Disconnection		
%UXa.b.163	_ab_CH3_IDD	CH3 Input Disconnection	Б	$A/D \rightarrow$
%UXa.b.164	_ab_CH4_IDD	CH4 Input Disconnection	ĸ	CPU
%UXa.b.165	_ab_CH5_IDD	CH5 Input Disconnection		
%UXa.b.166	_ab_CH6_IDD	CH6 Input Disconnection		
%UXa.b.167	_ab_CH7_IDD	CH7 Input Disconnection		
%UXa.b.176	_ab_ERR_CLR	Error clear request	W	CPU → A/D

In the address assigned, 'a' denotes the Base No. and 'b' denotes the Slot No. on which the module is installed.

In order to read 'CH1 digital value' of A/D conversion module installed on Base No. 0, Slot No. 4, it is displayed as %UW0.4.3.

In order to read 'CH4 Input disconnection' of A/D conversion module installed on Base No. 0, Slot No. 5, it is displayed as %UX0.5.164.

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Setting area of Run parameters

The following table lists the details of the setting area of A/D conversion module's Run parameters.

Memory Address		Detaile	D/M/	Domorko
Hex	Dec	Details	FC/ VV	Remarks
0н	0	Channel enable/disable setting	R/W	PUT
1 _H	1	Setting range of input voltage/current	R/W	PUT
2 _H	2	Output data format setting	R/W	PUT
3 _Н	3	Filter processing enable/disable setting	R/W	PUT
4 _H	4	CH0 filter constant	R/W	PUT
5 _H	5	CH1 filter constant		
6 _Н	6	CH2 filter constant		
7 _H	7	CH3 filter constant		
8 _H	8	CH4 filter constant		
9 _H	9	CH5 filter constant		
A _H	10	CH6 filter constant		
B _H	11	CH7 filter constant		
C _H	12	Average processing enable/disable setting	R/W	
D _H	13	Average processing method setting	R/W	
E _H	14	CH0 average value	R/W	PUT
F _H	15	CH1 average value		
10 _H	16	CH2 average value		
11 _H	17	CH3 average value		
12 _H	18	CH4 average value		

Table 6 – Setting area of run parameters

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5. Configuration and Function of Internal Memory 5.1. Internal memory configuration

Memory Address		Detaile		Domorko
Hex	Dec	Details	FK/ VV	Remarks
13 _H	19	CH5 average value		
14 _H	20	CH6 average value		
15 _н	21	CH7 average value		
16 _н	22	Error code	R/W	GET

Note: R/W indicates Read/Write if available from PLC program.

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5.2 I/O area of A/D converted data

Module Ready/Error (%UXa.b.0, %UXa.b.15; a: Base No., b: Slot No.)

%UXa.b.15: It is ON when PLC CPU is powered or reset with A/D conversion, ready to process A/D conversion.

%UXa.b.0: It is a flag to display the error status of A/D conversion module.



Module READY Bit ON (1): READY, Bit Off (0): NOT READY

Error information Bit ON (1): Error, Bit Off (0): Normal

Run channel (%UXa.b.16~23, a: Base No., b: Slot No.)

This area stores Enable/Disable (Run/Stop) information of individual channel.

	B31	B30	B29	B28	B27	B26	B25	B24	B23	B22	B21	B20	B19	B18	B17	B16
									С	C	С	С	С	С	C	C
6UXa.b.16~23	-	-	—	—	—	-	-	—	н	н	н	н	н	н	н	н
									7	6	5	4	3	2	1	0

Run channel information Bit ON (1): During Run, Bit Off (0): Operation Stop

Digital output value (%UWa.b.2 ~9, a: Base No., b: Slot No.)

A/D conversion value is output to buffer memory addresses $2 \sim 9$ (%UWa.b.2 ~9) for respective channels.

Digital output value is saved in 16-bit binary.

5.2. I/O area of A/D converted data

%UWa.b.2~9	B15	814	B13	B12	811	B10	89	B8	87	B 6	85	B4	B3	82	81	B 0
700Wa.b.2.09						Cha	nnel	# dig	jital v	alue						

Address	Details
%UWa.b.2	CH0 digital value
%UWa.b.3	CH1 digital value
%UWa.b.4	CH2 digital value
%UWa.b.5	CH3 digital value
%UWa.b.6	CH4 digital value
%UWa.b.7	CH5 digital value
%UWa.b.8	CH6 digital value
%UWa.b.9	CH7 digital value

Detect input signal failure/disconnect flag (%UXa.b.160~167 a: Base No., b: Slot No.)

Failure/disconnect status bit for respective input channels is saved in %UXa.b.

Each bit is set to 1 if an assigned channel is detected as disconnected, and it is reset to 0 if connected back. In addition, this bit can be used in the program, together with execution conditions.

	B176	B175	B17	4 B73	B172	B171	B170	B169	B167	B166	B165	B164	B163	B162	B161	B160
									С	С	С	С	С	С	С	С
%UXa.b.160~167	—	_	_	_	-	_	_	_	н	н	н	н	н	н	Н	Н
					_				7	6	5	4	3	2	1	0
	<u> </u>	ı														

BIT	Description
0	Normal
1	Disconnection

Error clear request flag (%UXa.b.176, a: Base No., b: Slot No.)

Whenever a parameter setting error occurs in the A/D module (for example, incorrect filter constant), the RUN LED starts blinking and the error code would be set in address No. 22. This error code/status is not automatically cleared, even if parameter setting errors are rectified. The error status/code is cleared when the CPU provides an 'error clear request' (%UXa.b.176 bit ON) to the module. Once the error status is cleared, RUN LED returns to steady On status.

The flag 'error clear request' should always be used together with %UXa.b for correct operation as in the below example.



5.3. Operation parameters settings area

5.3 Operation parameters settings area

One word (2 bytes) is assigned for each address in the internal memory, which can be displayed in 16 bits. Each of the 16 bits can be set: On - '1' or Off - '0' for various functions.

Address 0 - A/D conversion enable/disable status for each channel

Enable/disable status of A/D conversion for each channel can be set as below:

1. Set all unused channels as 'Disable'. This saves the conversion cycle time.

	B15	B14	B13	B12	B11	B10	B9	B8	B7	B6	B5	B4	B3	B2	B1	B0
									С	С	С	С	С	С	С	С
Address "0"	—	_	_	_	-	—	—	—	н	н	Н	н	Н	Н	Н	Н
					_				7	6	5	4	3	2	1	0

BIT	Description
0	Disable
1	Enable

2. $B8 \sim B15$ bits are reserved for future use.

Address 1 - Input voltage/current range

- 1. The range of analog input voltage/current is specified for each channel.
- 2. If the analog input range is not specified, the range of all the channels is set to $1 \sim 5V$ (or $4 \sim 20$ mA).
- 3. Setting range of analog input voltage/current is as explained below.

5. Configuration and Function of Internal Memory 5.3. Operation parameters settings area

2MLF-AV8A

	B15	B14	B13	B12	B11	B10	B9	B 8	B7	B6	B5	B4	B3	B2	B1	B0
	C		C		C	;	C	;	()	C)	C	;	C	;
Address "1"	н		ŀ	ł	Н		Н		Н		Н		Н		Н	
	7		6		5		4		3		2		1		0)
	<u> </u>						_									

BIT	Description
00	1 V ~ 5 V
01	0 V ~ 5 V
10	0 V ~ 10 V
11	-10 V ~ 10 V

5. Configuration and Function of Internal Memory 5.3. Operation parameters settings area

2MLF-AC8A

	B15 B14	B13 B12	B11 B10	B9 B8	B7 B6	B5 B4	B3 B2	B1 B0
	С	С	С	С	С	С	С	С
Address ""	н	н	н	н	н	н	н	н
	7	6	5	4	3	2	1	0

BIT	Description
00	4 mA~ 20 mA
01	0 mA ~ 20 mA

Address 2 - Output data format

The range of digital output data for analog input is specified for each channel.

- 1. If the output data range is not specified, the range of all the channels is set to $0 \sim 16000$.
- 2. Setting range of digital output data range is as explained below.

	B15	B14	B13	B12	B11	B10	B9	B 8	B7	B 6	B5	B4	B3	B2	B1	B0		
	C	С		;	C	С		С		С			С		C	;		
Address "2"	Н		H	Н		1	H	ł	ŀ	ł	H	ł	F	I	H			
	7		6		5		5		4		3		2		1		0	

BIT	Description
00	0 ~ 16000
01	-8000 ~ 8000
10	Precise Value
11	0 ~ 10000

Precise value has the following digital output ranges for the analog input range.

2MLF-AV8A	1
-----------	---

Analog input	-10 ~ 10V	0 ~ 10V	0 ~ 5V	1 ~ 5V
Precise Value	-10000 ~ 10000	0 ~ 10000	0 ~ 5000	1000 ~ 5000

2MLF-AC8A

Analog input	4 ~ 20mA	0 ~ 20mA
Digital output		
Precise Value	4000 ~ 20000	0 ~ 20000

5.3. Operation parameters settings area

Address 3 - Filter process Enable/Disable

The Enable/Disable status of filter process is specified for each channel.

- 1. If the filter process is not specified, all the channels are sampled.
- 2. Setting of the filter process is as explained below.

	B15	B14	B13	B12	B11	B10	B9	B8	B7	B6	B5	B4	B3	B2	B1	B0
<i></i>									С	С	С	С	С	С	С	С
Address "3"	—	—	—	—	—	_	_	—	Н	Н	Н	Н	Н	Н	Н	Н
									7	6	5	4	3	2	1	0
																/

BIT	Description
0	Disable
1	Enable

Address 4-11 - Filter constant

Default value of the filter constant is 1. Setting range for the filter constant is $1 \sim 99$.

If any other value exceeding the setting range is specified, error code 50# is displayed on error code address 22.

If the filter constant is not specified, the filter constant is set to '1'.

Setting of the filter constant is as explained below.

5. Configuration and Function of Internal Memory 5.3. Operation parameters settings area

Address "4 ~ 11"	B15	B14	B13	B12	B11	B10	B9	B8	B7	B6	B5	B4	B3	B2	B1	B0
	—	_	_	—	_	—	—	—			Chan	nel#	filter	value		

Address Details Address No. 4 CH0 filter value Address No. 5 CH1 filter value Address No. 6 CH2 filter value Address No. 7 CH3 filter value Address No. 8 CH4 filter value CH5 filter value Address No. 9 CH6 filter value Address No. 10 Address No. 11 CH7 filter value

Setting range of filter constant is 1 \sim 99



ATTENTION

These filter constants are effective only when the filter process is set to 'Enable'.

Address 12 - Average process Enable/Disable

The Enable/Disable status of average process is specified for each channel.

If the average process is not specified, all the channels are sampled.

Setting of the average process is as explained below.

	B15	B14	B13	B12	B11	B10	B9	B8	B7	B6	B5	B4	B3	B2	B1	B0
									С	С	С	С	С	C	С	С
Address "12"	—	—	—	—	—	—	—	—	н	н	н	н	н	Н	н	н
									7	6	5	4	3	2	1	0

BIT	Description
0	Disable
1	Enable

5.3. Operation parameters settings area

Address 13 - Average process method (address number 13)

This area is used for specifying average processing method. The available options are count average and time average. If neither is specified, all the channels are set to count average process by default.

	B15	B14	B13	B12	B11	B10	B9	B8	B7	B6	B5	B4	B3	B2	B1	B0
									С	С	С	С	С	С	С	С
Address 13	—	—	—	—	—	—	—	—	Н	Н	Н	Н	Н	Н	Н	Н
									7	6	5	4	3	2	1	0
																/
		F	RIT						Г	Desc	rintic	n				
										2000	npue	211				_
			0						Co	unt	aver	age				
			1						Ti	me a	avera	age				



ATTENTION

This setting is effective only when the average process is set to 'Enable'.

Address 14-21 - Average value

Setting range of time/count average's constant value is explained as follows:

- Setting range of time average: $4 \sim 16000 \text{ (ms)}$
- Setting range of count average: 2 ~ 64000 (times)

If it exceeds the range:

- 1. Error No. 60X is generated if time average range is exceeded.
- 2. Error No. 70X is generated if count average range is exceeded.

The above error codes are available on address 22. If the above error occurs, the default values are applied for average processing.

Default values are time average: 4, Frequency average: 2

The process value of time/count average is as stored below:

5. Configuration and Function of Internal Memory 5.3. Operation parameters settings area

Address "14 ~ 21"	B15	B14	B13	B12	B11	B10	B9	B8	B7	B6	B5	B4	B3	B2	B1	B0
	—	—	—	—	—	—	_	_		C	hann	el# av	/erag	e valı	Je	

Setting range of time average process value is 4 \sim 16000 Setting range of count average process value is 2 \sim 64000

Address	Details
14	CH0 average value
15	CH1 average value
16	CH2 average value
17	CH3 average value
18	CH4 average value
19	CH5 average value
20	CH6 average value
21	CH7 average value



ATTENTION

This setting is effective only when the average process method (time or count) is set to 'Enable'.

Error code (address number 22)

When the A/D conversion module detects any error, during operation, it generates an error code and saves it in Address 22.

5.3. Operation parameters settings area



Refer to the table below for detailed error codes.

Error Code (Dec)	Error Details	Remarks
0	Normal Run	RUN LED On
20	Module error (A/D Conversion Error)	RUN LED flickers every 0.2 sec.
40#	Offset value with the range of $1 \sim 5 V (4 \sim 20 \text{ mA})$ is set greater than or equal to Gain value.	
41#	Offset value with the range of $0 \sim 5 V (0 \sim 20 mA)$ is set greater than or equal to Gain value.	
42#	Offset value with the range of 0 ~ 10 V is set greater than or equal to Gain value.	RUN LED flickers every 1
43#	Offset value with the range of -10 ~ 10 V is set greater than or equal to Gain value.	SEC.
50#	Filter constant setting range exceeded	
60#	Time average setting range exceeded	
70#	Count average setting range exceeded	
80#	Analog input range setting error	Applied to 2MLF-AC8A



ATTENTION

- 1. # denotes the channel with error found.
- 2. For more details of error codes, refer to section Troubleshooting.
- 3. If more than two errors occur, the module saves only the first error code.
- Once the cause of error condition is rectified, use the flag 'error clear 4. request' to clear the error code and this changes the RUN LED return to steady ON. For more information, refer to section Error Clear request flag (UXY.11.0, X: Base No., Y: Slot No.).

5.4 Global variable (data area)

How to use global variable

There are two ways to register a global variable.

- Automatic registration after I/O parameter setting at project window
- Batch registration after I/O parameter setting

For automatic registration and batch registration, refer to section Registering special module variables.

Local variable registration

You can register the variables as local variables among registered global variables.

To register local variables in I/O parameter, perform the following steps.

Step	Action
1	In the Project Window, double-click Local Variables under Scan Program.
2	Right-click in the local variable window and click Add EXTERNAL variable.

5.4. Global variable (data area)



3 Select local variable to add at Global View on Add External Variable window ('All' or 'Base, slot').

Example:

In the following figure, select the digital input value (_0102_CH0_DATA) of "Base01, Slot02".

5. Configuration and Function of Internal Memory 5.4. Global variable (data area)

	Action					
Add Ex	ternal '	Variable				_?
<u>F</u> ind Varia	able:					ОК
_ Global \	√ariable I	tem				Cancel
<u>I</u> tem:	Base	01, Slot02: 2MLF-	AV8A (Voltage, 8-CH)	•	<u>S</u> elect All
	· · ·					<u>U</u> nselect A
	Apply	Variable Kind	Variable Name	Туре	Ad	
1		VAR_GLOBAL	_0102_CH0_ACT	BOOL	%UX1	
2	▼	VAR_GLOBAL	_0102_CH0_DAT	INT	%UW1	
3		VAR_GLOBAL	_0102_CH0_HO	BOOL	%UX1	
4	Γ	VAR_GLOBAL	_0102_CH0_IDD	BOOL	%UX1	
5	Γ	VAR_GLOBAL	_0102_CH0_LO	BOOL	%UX1	
6		VAR_GLOBAL	_0102_CH1_ACT	BOOL	%UX1	
7		VAR_GLOBAL	_0102_CH1_DAT	INT	%UW1	
8		VAR_GLOBAL	_0102_CH1_HO	BOOL	%UX1	
9		VAR_GLOBAL	_0102_CH1_IDD	BOOL	%UX1	
10		VAR_GLOBAL	_0102_CH1_LO	BOOL	%UX1	
11		VAR_GLOBAL	_0102_CH2_ACT	BOOL	%UX1	
12		VAR_GLOBAL	_0102_CH2_DAT	INT	%UW1	
13		VAR_GLOBAL	_0102_CH2_HO	BOOL	%UX1	
14		VAR_GLOBAL	_0102_CH2_IDD	BOOL	%UX1	
	-	hun apanul	0400 0110 1.0		i an a su più	

How to use local variables

This section describes the how to add a global variable at local program.

The following is an example for getting the conversion value of CH0 of A/D conversion module to %MW0.

1. By using the following MOVE function, double-click variable part ahead of IN, then **Select Variable** window displays.

5.4. Global variable (data area)



2. On **Select Variable** window, select global variable under **Variable List** and select relevant base (8 base, 4 slot) at global variable view item.

🛄 Seleo	t Variable					? 🛛
⊻ariable	Name: sdd	Add to address cor	nment			ОК
Variab	le List					Cancel
OLoc	al Variable 💿 Global Variable (Address Comment	ag			
						New Variable
						Edit Variable
Lis <u>t</u> :	ALL	~				Dalata Madable
	ALL	1000 Million				
	General Variabes	1.4.000				
	Base07, Slot02: 2MLF-TC4S (Isolate Dase07, Slot02: 2MLF-DD4A (NTD,	(d, 4-CH) (4-CH)	Type	Address	Initial Valu	
1	Base07, Slot04: 2MLF-DC4A (Currer	nt, 4-CH)	BOOL	%LIX7.2.16		
2	VABase08, Slot02: 2MLF-AU8A (Lurren VABase08, Slot03: 2MLF-DC8A (Curren	1t, 8-CH) 1t 8-CH)	BOOL	%UX7.2.0		
3	VABase08, Slot04: 2MLF-HO2A (Open-	Collector, 2-CH)	BOOL	%UX7.2.468		
4	Base08, Slot05: 2MLF-AV8A (Voltag	e, 8-CH)	BOOL	%UX7.2.400		
5	VAR GLOBAL	0702_CH0_DOOT	BOOL	%UX7.2.20		
6			INIT	%UN/7.2.404		
7		0702_CH0_MAX	INT	%UW7.2.13		
0			POOL	%UV7.2.12		
0		0702_CH0_FAH	BOOL	%UX7.2.34		
10	VAR GLOBAL	0702_CH0_PAI	BOOL	%UX7.2.33		
11			BOOL	%UX7.2.33		
12		0702_010_FALL	BOOL	%UY7.2.49		
12		0702_CH0_RAI	BOOL	%UY7.2.48		
14		0702_010_1AL	BOOL	%UX7.2.472		
15		0702_CH0_C0000	INT	%1/w/7.2.8		
15		0702_010_00AL	BOOL	%UY7.2.0		
17		0702_0H0_0ETERN	INT	%1/w/7.2.24		
18				%UD7.2.4	~	
<	TVAN GLODAL				>	

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Honevwell	

3. Double-click or select _0805_CH4_DATA corresponding to CH4 A/D conversion data and click **OK**.

Selec	ct Variable					?
⊻ariable	Name: 0805_CF4_DATA	Add to address c	omment			ОК
Variab	ile List					Cancel
OLoc	cal Variable 💿 🙆 Global Variable	O <u>A</u> ddress Comment O	Elag			New Variable
List		(-k 0 CU)				Edit Variable.
	Daseuo, Siotus: ZMLF-AYOA (Y	voitage, o-CH)	<u> </u>			Delete Variabl
	Variable Kind	Variable Name	Туре	Address	Initial Valu 🔨	
1	VAR_GLOBAL	_0805_CH0_ACT	BOOL	%UX8.5.16		
2	VAR_GLOBAL	_0805_CH0_DATA	INT	%UW8.5.2		
3	VAR_GLOBAL	_0805_CH0_IDD	BOOL	%UX8.5.160		
4	VAR_GLOBAL	_0805_CH1_ACT	BOOL	%UX8.5.17		
5	VAR_GLOBAL	_0805_CH1_DATA	INT	%UW8.5.3		
6	VAR_GLOBAL	_0805_CH1_IDD	BOOL	%UX8.5.161		
7	VAR_GLOBAL	_0805_CH2_ACT	BOOL	%UX8.5.18		
8	VAR_GLOBAL	_0805_CH2_DATA	INT	%UW8.5.4		
9	VAR_GLOBAL	_0805_CH2_IDD	BOOL	%UX8.5.162		
10	VAR_GLOBAL	_0805_CH3_ACT	BOOL	%UX8.5.19		
11	VAR_GLOBAL	_0805_CH3_DATA	INT	%UW8.5.5		
12	VAR_GLOBAL	_0805_CH3_IDD	BOOL	%UX8.5.163		
13	VAR_GLOBAL	_0805_CH4_ACT	BOOL	%UX8.5.20		
14	VAR_GLOBAL	_0805_CH4_DATA	INT	%UW8.5.6		
15	VAR_GLOBAL	_0805_CH4_IDD	BOOL	%UX8.5.164		
16	VAR_GLOBAL	_0805_CH5_ACT	BOOL	%UX8.5.21		
17	VAR_GLOBAL	_0805_CH5_DATA	INT	%UW8.5.7		
18	VAR GLOBAL	0805 CH5 IDD	BOOL	%UX8.5.165	×	

4. The following figure is the result of adding global variable corresponding to CH0 A/D conversion value.

Channel	M	OVE	
	EN	ENO	
_0000_CH 0_DATA -	IN	OUT-	%MW0

5. Configuration and Function of Internal Memory 5.5. PUT/GET function block use area (parameter area)

5.5 PUT/GET function block use area (parameter area)

The following table describes operation parameter setting area of A/D conversion module.

Global Variable	Contents	Read/Write	Instruction
_Fab_CH_EN	Channel Enable/Disable	Read/Write	PUT
_Fab_IN_RANGE	Input current/ voltage ranges setting	Read/Write	PUT
_Fab_DATA_TYPE	Output data type setting	Read/Write	PUT
_Fab_FILT_EN	Filter processing enable/disable setting	Read/Write	PUT
_Fab_CH0_FILT_CON ST	CH0 filter constant setting	Read/Write	PUT
_Fab_CH1_FILT_CON ST	CH1 filter constant setting		
_Fab_CH2_FILT_CON ST	CH2 filter constant setting		
_Fab_CH3_FILT_CON ST	CH3 filter constant setting		
_Fab_CH4_FILT_CON ST	CH4 filter constant setting		
_Fab_CH5_FILT_CON ST	CH5 filter constant setting		
_Fab_CH6_FILT_CON ST	CH6 filter constant setting		
_Fab_CH7_FILT_CON ST	CH7 filter constant setting		
_Fab_AVG_EN	Average processing enable/disable setting	Read/Write	PUT

5. Configuration and Function of Internal Memory 5.5. PUT/GET function block use area (parameter area)

Global Variable	Contents	Read/Write	Instruction
_Fab_AVG_SEL	Average processing method setting	Read/Write	
_Fab_CH0_AVG_VAL	CH0 average value setting	Read/Write	
_Fab_CH1_AVG_VAL	CH1 average value setting		
_Fab_CH2_AVG_VAL	CH2 average value setting		
_Fab_CH3_AVG_VAL	CH3 average value setting		
_Fab_CH4_AVG_VAL	CH4 average value setting		
_Fab_CH5_AVG_VAL	CH5 average value		
_Fab_CH6_AVG_VAL	CH6 average value setting		
_Fab_CH7_AVG_VAL	CH7 average value setting		
_Fab_ERR_CODE	Error codes	Read/Write	GET

At device allocation, 'a' means base number and 'b' means slot number where module is equipped.

PUT instruction

Using PUT instruction, write data to special module.

		PUT		
800L -	REQ		DONE	- BOOL
USINT -	BASE		STAT	- UINT
USINT -	SLOT			
UINT -	MADDR			
*ANY —	DATA			

*ANY: WORD, DWORD, INT, USINT, DINT, UDINT type available among ANY type

Input

- REQ: execute function when 1
- BASE: set base position
- SLOT: set slot position
- MADDR: module address
- DATA: data to save module

Output

DONE: Output 1 when normal

STAT: Error information

Function

This instruction is used for reading data from designated special module.

Function Block	Input (ANY) Type	Description
PUT_WORD	WORD	Save WRD data into the designated module address (MADDR).
PUT_DWORD	DWORD	Save DWORD data into the designated module address (MADDR).
PUT_INT	INT	Save INT data into the designated module address (MADDR).
PUT_UINT	UINT	Save UNIT data into the designated module address (MADDR).
PUT_DINT	DINT	Save DINT data into the designated module address (MADDR).
PUT_UDINT	UDINT	Save UDINT data into the designated module address (MADDR).

GET instruction

Using GET instruction, read from special module data.



*ANY: WORD, DWORD, INT, UINT, DINT, UDINT type available among ANY type

Input

REQ: execute function when 1

BASE: set base position

SLOT: set slot position

MADDR: module address

512(0x200) ~ 1023(0x3FF)

Output

DONE: output 1 when normal

STAT: Error information

DATA: data to read from module

Function

This instruction is used for reading data from designated special module.

Function Block	Output (ANY) Type	Description
GET_WORD	WORD	Read data as much as WORD from the designated module address (MADDR).
GET_DWORD	DWORD	Read data as much as DWORD from the designated module address (MADDR).

5. Configuration and Function of Internal Memory 5.5. PUT/GET function block use area (parameter area)

Function Block	Output (ANY) Type	Description
GET_INT	INT	Read data as much as INT from the designated module address (MADDR).
GET_UINT	UINT	Read data as much as UNIT from the designated module address (MADDR).
GET_DINT	DINT	Read data as much as DINT from the designated module address (MADDR).
GET_UDINT	UDINT	Read data as much as UDINT from the designated module address (MADDR).

Example using PUT/GET instruction

Enable channel

- 1. You can enable/disable A/D conversion per channel.
- 2. Disable channel to reduce the conversion cycle per channel.
- 3. When channels not designated, all channels are set as not used.
- Enable/disable of A/D conversion is as follows. 4.

B15	B14	B13	B12	B11	B10	B9	B8	B7	B6	B5	B4	B3	B2	B1	B0
-	-	-	-	-	-	-	-	CH7	CH6	CH5	CH4	CH3	CH2	CH1	CH0

BIT	Description							
0	Stop							
1	Run							





- 5. The value in B8~B15 is ignored.
- 6. The above figure is an example for enabling CH0~CH3 of A/D module equipped at slot 0.

Input voltage/current range setting

- 1. You can set input voltage/current range per channel.
- 2. When analog input range is not set, all channels are set as $1 \sim 5V (4 \sim 20 \text{mA})$.
- 3. Setting of analog input voltage/current range is as follows.
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The following is an example for setting CH0~CH3 as 1~5V and CH4~CH7 as 0~10V.

B15	B14	B13	B12	B11	B10	В9	B8	B7	B6	B5	B4	B3	B2	B1	B0
CH7		CH6		CH5		CH4		CH3		CH2		CH1		CH0	

BIT	Description
00	1V ~ 5V
01	0V ~ 5V

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5. Configuration and Function of Internal Memory 5.5. PUT/GET function block use area (parameter area)

10	0V ~ 10V
11	-10V ~ 10V

16#AA00 : 1010 1010 0000 0000



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The following figure is an example for setting CH0~CH3 as 4~20mA and CH4~CH7 as 0~20mA.

B15	B14	B13	B12	B11	B10	B9	B8	B7	B6	B5	B4	B3	B2	B1	B0
CH7		CH6		CH5		CH4		CH3		CH2		CH1		CH0	

BIT	Description
00	4mA ~ 20mA
01	0mA ~ 20mA

16#AA00 : 1010 1010 0000 0000 Ţ 7

CH7, CH6, CH5, CH4, CH3, CH2, CH1, CH0



Output data range setting

- 1. Digital output data range for analog input can be set per channel.
- 2. When output data range is not set, all channels are set as $0\sim16000$.
- 3. The following figure is an example for setting CH0~CH3 as -8000~8000, CH4~CH7 as 0~10000.

B15	B14	B13	B12	B11	B10	B9	B8	B7	B6	B5	B4	B3	B2	B1	B0
CH7		CH6		CH5		CH4		CH3		CH2		CH1		CH0	

BIT	Description
00	Unsigned value:0 ~ 16000
01	Signed value:-8000 ~ 8000
10	Precise value
11	Percentile value:0 ~ 10000

5.5. PUT/GET function block use area (parameter area)



Precise value has the following digital output range for analog input range.

Analog input Digital output	-10 ~ 10V	0 ~ 10V	0 ~ 5V	-1 ~ 5V
Precise value	-10000 ~ 10000	0 ~ 10000	0 ~ 5000	1000 ~ 5000

2MLF-AC8A

Analog input Digital output	4 ~ 20mA	0 ~ 20mA
Precise value	4000 ~ 20000	0 ~ 20000

Filter process setting

_

- 1. You can enable/disable filter process per channel.
- 2. If filter process is not set; all channels are set as enable.
- 3. The following figure is an example for using filter CH4.

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5. Configuration and Function of Internal Memory 5.5. PUT/GET function block use area (parameter area)

B15	B14	B13	B12	B11	B10	B9	B8	B7	B6	B5	B4	B3	B2	B1	B0
-	-	-	-	-	-	-	-	CH7	CH6	CH5	CH4	CH3	CH2	CH1	CH0

BIT	Description
0	Disable
1	Enable

16#0010 : 0000 0000 0001 0000



Filter constant setting

- 1. Initial value of filter constant is 1.
- 2. Setting range of filter constant is 1~99.
- 3. When setting value other than setting range, it indicates error number 50# at error code indication address (22). At this time, A/D conversion value keeps previous data. (# means the channel where error occurs at error code.)
- 4. If filter constant is not set; filter constant is set as '1'.
- 5. The following figure is an example for setting filter constant as 9 at channel 0.

5.5. PUT/GET function block use area (parameter area)

B15	B14	B13	B12	B11	B10	B9	B8	B7	B6	B5	B4	B3	B2	B1	В0
-	-	-	-	-	-	-	-	CH# fil	ter consta	ant					

Address	Description
_Fab_CH0_FILT_CONST	CH0 filter constant setting
_Fab_CH1_FILT_CONST	CH1 filter constant setting
_Fab_CH2_FILT_CONST	CH2 filter constant setting
_Fab_CH3_FILT_CONST	CH3 filter constant setting
_Fab_CH4_FILT_CONST	CH4 filter constant setting
_Fab_CH5_FILT_CONST	CH5 filter constant setting
_Fab_CH6_FILT_CONST	CH6 filter constant setting
_Fab_CH7_FILT_CONST	CH7 filter constant setting

At device allocation, 'a' means base number, 'b' means slot number where module is equipped.

ATTENTION

For filter constant to be an effective value, enable the filter process.



5. Configuration and Function of Internal Memory 5.5. PUT/GET function block use area (parameter area)

Average process setting

- 1. You can enable/disable average process per channel.
- 2. When disabling the average process, all channels are set as sampling process.
- 3. The following figure is an example for setting average process for channel 7.

B15	B14	B13	B12	B11	B10	B9	B8	B7	B6	B5	B4	B3	B2	B1	B0
-	-	-	-	-	-	-	-	CH7	CH6	CH5	CH4	CH3	CH2	CH1	CH0



Average process method setting

- 1. In average process method, there are Count average, and Time average.
- 2. All channels execute average process by Count if Time/Count average process is not set.

5.5. PUT/GET function block use area (parameter area)

3.	The following figure is an example setting for CH0~CH3 as count average and	
	CH4~CH7 as time average.	

B15	B14	B13	B12	B11	B10	В9	B8	B7	B6	B5	B4	B3	B2	B1	B0
-	-	-	-	-	-	-	-	CH7	CH6	CH5	CH4	CH3	CH2	CH1	CH0

BIT	Description
0	Count average
1	Time average

16#00F0 : 0000 0000 1111 0000





ATTENTION

For setting average process by Time/Count, enable average process.

Average value setting

- 1. Constant value setting range of Time/Count is as follows:
 - Time average setting range: $4 \sim 16000$ (ms)
 - Count average setting range: $2 \sim 64000$ (times)

- 2. In case of setting value other than setting range:
 - If time average setting range exceeds, then error number 60x shows up.
 - If count average setting range exceeds, then error number 70x shows up. At this time, initial value is applied and calculated.

The following figure is an example for setting count average as 30 at channel 1.

3. If the Time/Count average process value is not set, initial value is applied and calculated (Time average: 4, Count average: 2).

B15	B14	B13	B12	B11	B10	B9	B8	B7	B6	B5	B4	B3	B2	B1	B0
-	-	-	-	-	-	-	-	CH# filt	ter consta	int					

Address	Description
_Fab_CH0_AVG_VAL	CH0 average process value setting
_Fab_CH1_AVG_VAL	CH1 average process value setting
_Fab_CH2_AVG_VAL	CH2 average process value setting
_Fab_CH3_AVG_VAL	CH3 average process value setting
_Fab_CH4_AVG_VAL	CH4 average process value setting
_Fab_CH5_AVG_VAL	CH5 average process value setting
_Fab_CH6_AVG_VAL	CH6 average process value setting
_Fab_CH7_AVG_VAL	CH7 average process value setting
_Fab_CH0_AVG_	VAL CH0 average process value setting

At device allocation, 'a' means base number, 'b' means slot number, where module is installed.

4.

5. Configuration and Function of Internal Memory 5.5. PUT/GET function block use area (parameter area)





ATTENTION

For setting Time/Count average process value, enable average process.

Error code

- 1. Saves error code detected at A/D conversion module.
- 2. The following figure is a program example for reading error code

B15	B14	B13	B12	B11	B10	B9	B8	B7	B6	B5	B4	B3	B2	B1	B0
-	-	-	-	-	-	-	-	Error C	Code						

Error Code (Decimal)	Error Contents	Remark
0	Normal RUN	RUN LED on
20	Module error (A/D Conversion Error)	RUN LED flickers every 0.2s
40#	Offset value of 1~5V (4~20mA) range is set as larger or equal than gain value	

5.5. PUT/GET function block use area (parameter area)

Error Code (Decimal)	Error Contents	Remark
41#	Offset value of 0~5V (0~20mA) range is set as larger or equal than gain value	
42#	Offset value of 0~10V range is set as larger or equal than gain value	RUN LED flickers every 1s
43#	Offset value of -10~10V range is set as larger or equal than gain value	
50#	Filter constant setting range exceeded	
60#	Time average setting range exceeded	
70#	Count average setting range exceeded	
80#	Analog input range setting error	Applied at 2MLF-AC8A

At error code, # indicates channel where error occurs.

E.

REFERENCE - INTERNAL For more details on error code, refer to section Error Codes.

- 3. In case, two error code occurs, module saves first occurred error code and later occurred error code is not saved
- 4. In case error occurs, after modifying error, use error clear request flag, restart power to delete error code and stop LED flicker. For more details about error clear request flag, refer to Error Clear request Flag (%UXa.b.176, a: Base No, b: Slot No.).

6. Programming

Read/Write of operation parameter settings area 6.1

Read operation parameters settings area (GET, GETP command)

The below program examples of read/write commands (GET/PUT) for data transfer between CPU and I/O module. For example, configuration of internal memory, and so on.

Туре GET command Execution condition _____[GET n1 n2 D n3 Execution condition

Туре	Description	Area available				
n1	Slot number where the special module is installed	Integer				
n2	Start address of setting area of special module's Run parameters to read data.	Integer				
D	Device's start address with saved data to read	M, P, K, L, T, C, D, #D				
n3	Number of words data to read	Integer				
< Difference between GET command and GETP command >						

)

Difference between GET command and GETP command

GET: Always executed with execution condition On (

GETP: Executed with execution condition of operation start (

Example

The below program example reads A/D conversion module (Base 0, Slot 3) memory addresses 0 and 1 and transfers to D0 and D1 of CPU module.

6. Programming

6.1. Read/Write of operation parameter settings area

(Addr	ress) D area of CPU module		Internal memory (A	ddress)
D0	CH enable/disable setting	•	CH enable/disable setting	0
D1	Range setting of input voltage/ current	←	Range setting of input voltage/ current	1
	-		-	
	-		-	
	-		-	

100000 	GET	3	0	D00000	2
					END

Write operation parameters settings area (PUT, PUTP command)



Туре	Description	Area available
n1	Slot number where the special module is installed	Integer
n2	Start address of special module's internal memory to write data.	Integer
S	Device's start address or integer with saved data to write.	M,P,K,L,T,C,D,# D,integer
n3	Number of word data to write	Integer

< Difference between PUT command and PUTP command >

PUT: Always executed with execution condition On (

PUTP: Executed with execution condition of operation start (

Example

) –
The below program example reads $D10 \sim D13$ of CPU module and writes to A/D

(Addı	ress) D area of CPU module	 Internal memory (A	(ddress)
D10	Average processing	 Average processing	12
010	enable/disable setting	enable/disable setting	12
D11	Average processing method setting	 Average processing method setting	13
D12	CH0 average value setting	 CH0 average value setting	14
D13	CH1 average value setting	 CH1 average value setting	15
	-	-	

conversion module (Base 0, Slot 6) memory addresses $12 \sim 15$.

M00000		PUTP	6	12	D00010	4
						END

6.2. Configuring A/D module through program method

6.2 Configuring A/D module through program method

2MLF-AV8A

1. This program example accesses the A/D conversion value from CPU memory U02.02~U02.09 (Base 0, Slot 2) and directly reads the error code from Address 22 in the module.



2. This program example shows the procedure to configure the A/D voltage to digital conversion module by program method. That is, using PUT/GET commands to transfer data between CPU and module internal memory.

		Siol No. Interr	nal memory a	Selling dala	The num	iber of dala lo write /
U02,00,F P00000	PUT	2	0	h0019	1	Used CH selling (CH0,3,4)
Module READY Execution contact	PUT	2	1	NEFEE	1	Inputuollage range selling (-10-100)
	PUT	2	2	h0000	1	Oulpul dala range selling (-192×16191)
	PUT	2	3	h0019	1	Filler process selling (CHD, 3, 4)
PUT 2 4 10	10	1	CHD filler constant setting			
	PUT	2	7	20	1	CH3 filler constant setting
	PUT	2	8	50	1	CH+filler constant setting
	PUT	2	12	h0019	1	Auerage process selling (CH0,3,4)
	PUT	2	13	hOOFF	1	Auerage processing method setting
	PUT	2	14	1000	1	CHD average value selling
	PUT 2 17 2000 1	1	CH3 auerage ualue selling			
	PUT	2	18	4000	1	CH∔auerage ualue selling
1000014			·'		POB1	
			MOV	U02.02	D00000	C HD digilal oulpul
U02,01,3			MOV	U02,05	D00003	C H 3 digilal oulpul
U02.01.4		+ +	MOV	U02,06	D00004	CH+digilal oulpul
CH Runtlag	GET	2	22	M0000	1	
				(END	

2MLF-AC8A

This program example shows the procedure to configure the A/D current to digital conversion module by program method. That is, using PUT/GET commands to transfer data between CPU and module internal memory.

6. Programming 6.2. Configuring A/D module through program method

		s	NolNo.		Selling dala	The nu	umber of dala lo write
			hi	ernal memory.	ad d re ss	/	*
U02.00.F P00000		PUT	2	0	h0019	1	Used CH selling (CHD,3,4)
Module READY		PUT	2	1	h5555	1	Input current range setting
Execution contact		PUT	2	2	h0000	1	Oulpul dala range selling (-192×16191)
		PUT	2	3	h0019	1	Filler process selling (CH0,3,+)
		PUT	2	4	10	1	CHO filler constant setting
		PUT	2	7	20	1	CH3 filler constant setting
		PUT	2	8	50	1	CH+filler constant setting
		PUT	2	12	N0019	1	Auerage process selling (C H0,3,+)
		PUT	2	13	hooff	1	Auerage processing method selling
		PUT	2	14	1000	1	CHD average value selling
		PUT	2	17	2000	1	CH3 average value selling
		PUT	2	18	4000	1	CH+auerage value selling
			-	i	i	IP00041	
P00041 U02,01,0			-	MOV	U02,02	D00000	C HD digilal oulpul
U02.01.3			1	MOV	U02,05	D00003	C H 3 digilal oulpul
U02,01,4			1	MOV	U02,06	D00004	CH+digilal oulpul
CH Runt	ag	GET	2	22	M0000	1	L
				· ·'	·'	END	L

6.3 Basic program

- It describes about setting the operation condition at internal memory of A/D conversion module.
- A/D conversion module is equipped at slot 2.
- I/O occupation points of A/D conversion module are 16 points (fixed type).
- Initial setting condition is saved at internal memory by 1 time input.

2MLF-AV8A

1. Program example using I/O Parameter.

I/O Parameter Setting - Fixed a	llocation(64points)			?
All Base Set Base All Base 00 : Default O : Default O : Default O : Default O : 2 MLF-AC8A (Curre O : Default D : D	Slot Module 0 1 2 2MLF-AC8A (Current, 8-CH', ▼) 3 4 5 6 7 8 3 10 11 11	Comment Inpu	t Filter Emergency Out	Allocation
	ete Slot Delete <u>B</u> ase Base <u>S</u> etting	1) Delete All Dețails		OK. Cancel

6. Programming 6.3. Basic program

2MLF-AC8A (Current, 8-CH	1)							?
2MLF-AC8A (Current, 8-CH)								
Parameter	CH 0	CH 1	CH 2	CH 3	CH 4	CH 5	CH 6	CH 7
📃 Input range	4~20mA	4~20mA	4~20mA	4~20mA	4~20mA	4~20mA	4~20mA	4~20mA
Output type	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000
Filter process	Enable	Disable	Disable	Enable	Enable	Disable	Disable	Disable
Filter constant	10	1	1	20	50	1	1	1
Average setting	Enable	Disable	Disable	Enable	Enable	Disable	Disable	Disable
Average processing	Time-Avr	Count-Avr	Count-Avr	Time-Avr	Time-Avr	Count-Avr	Count-Avr	Count-Avr
Average value	1000	2	2	2000	4000	2	2	2
, 2~64000							ОК	Cancel

6. Programming 6.3. Basic program



2. Program example using PUT/GET instruction.

6. Programming

6.3. Basic program



2MLF-AC8A

1. Program example using [I/O Parameter]

6. Programming

6.3. Basic program



6. Programming 6.3. Basic program

Module Ready Execution	CH RUN signal		
L0 _0002_RDY %MX100	<u> </u>		%MX101 (S)
4.1 %MX1010002_CH0_ ACT	MOVE EN ENO	Device to save data to send	
L2 _0002_CH0_ DATA	IN OUT - %MWO	CHO digital output	
L4 _0002_CH3_ ACT	MOVE	Device saving data to send	
L5 _0002_CH3_ DATA	. IN OUT . %%///O	CH3 digital output	
<i>L7</i> _0002_CH4_	MOVE		
<i>L8</i> _0002_CH4_ DATA	EN ENO.	CH 4 digital output	
L9 L10			
L11 Base No. 0	BASE STAT-		
Slot No. 2	SLOT DATA - %RWO	Reading error code	
L14 Internal memory	MADD		

Program example using PUT/GET instruction 2.

6. Programming 6.3. Basic program



6.4. Application program examples

6.4 Application program examples

Program to compare A/D conversion values

The following figure shows system configuration.

	2MLP-	2MLK-	2MLI-	2MLF-	2MLQ	
1	ACF2	CPU	D24A	AV8A	-	

Details of initial setting

No.	ltem	Details of Initial Setting	Internal Memory Address	Value to Write on Internal Memory
1	Used CH	CH0, CH2, CH4	0	'h0015' or '21'
2	Input voltage range	-10 ~ 10V	1	'hFFFF' or '65535'
3	Output data range	0 ~ 16000	2	'h0000' or '0'
4	4 Filter process CH0		3	'h0001' or '1'
5	CH0 filter constant	50	4	'h0032' or '50'
6	Average process	CH2, CH4	12	'h0014' or '20'
Average 7 processing method		Frequency average: CH2 Time average: CH4	13	'h0010' or '16'
8		Frequency average value: 100 (times)	16	'h0064' or '100'
0	Average value	Time average value: 200 (ms)	18	'h00C8' or '200'

Program description

- 1. If CH 0's digital value is less than 12000, Contact No. 0 (P00080) of relay output module installed on Slot No. 2 is ON.
- 2. If CH 2's digital value is greater than 13600, Contact No. 2 (P00082) of relay output module installed on Slot No. 2 is ON.
- 3. If CH 4's digital value is greater than or equal to 12000 and less than or equal to 13600, Contact No. 4 (P00084) of relay output module installed on Slot No. 2 is ON.
- 4. If CH 4's digital value is equal to 13600, Contact No. 5 (P00085) of relay output module installed on Slot No. 2 is ON.

Program

1. Program example using I/O Parameter.

I/O Parameter Setting - Fixed	allocatio	n(64points)				? 🛛
All Base Set Base						
🗊 Base 00 : Default 🛛 🔥	Slot	Module	Comment	Input Filter	Emergency Out	Allocation
00 : Default	0					
01 : Default	1					
02 : 2MLF-AV8A (Voltag	2 2	2MLF-AV8A (Voltage, 8-CH 💌			-	
03 : Default	3					
05 : Default	4					
	5					
00, Default	6					
08 ; Default	7					
09 : Default	8					
	9					
11 : Default 🧮	10					
🗇 Base 01 : Default	11					
Base 02 : Default						
🗂 Base 03 : Default 💽						
< >						
	lete Slot	Delete <u>B</u> ase Base <u>S</u> ettir	g Delete All	Details	Print V	OK. Cancel

6. Programming 6.4. Application program examples

2	MLF-AV8A (Voltage, 8-CH	0							? 🛛
	2MLF-AV8A (Voltage, 8-CH)								
	Parameter	CH 0	CH 1	CH 2	CH 3	CH 4	CH 5	CH 6	CH 7
	📃 Input range	-10~10V	1~5V	-10~10V	1~5V	-10~10V	1~5V	1~5V	1~5∀
	Output type	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000	0~16000
	Filter process	Enable	Disable						
	Filter constant	50	1	1	1	1	1	1	1
	Average setting	Disable	Disable	Enable	Disable	Enable	Disable	Disable	Disable
	Average processing	Count-Avr							
	Average value	2	2	100	2	200	2	2	2
:	2~64000							ОК	Cancel

6. Programming 6.4. Application program examples





Program to output error codes of analog input module to BCD display

The following figure shows system configuration.



Details of initial setting

- 1. Used CH: CH 0
- 2. Analog input current range: DC $4 \sim 20mA$
- 3. Time average process setting: 100ms
- 4. Digital output data range: $0 \sim 16000$

c Operation Setup	Retain Area Setling	Error Operation Setup	MODBUS Setup
	ion settings		Output control settings
mode	(1 ~ 999ms):	ms	✓ Output during debugging
Set Timer <u>W</u> atchdog (10 ~ 100) timer: 50 Oms)) ms	Keep output when an <u>e</u> rror occurs
Standard i	ngut filter:	3 💙 ms	Keep output when converting <u>B</u> UN->STOP
Restart Meth	nod estart 💽 War	m Bestart	Keep output when converting <u>STOP->RUN</u>
	<u></u>		

Program description

- 1. If P00000 is On, A/D conversion is initially specified.
- 2. If P00001 is On, A/D converted value and error code is saved, respectively, on D00000 and D00001.
- 3. If P00002 is ON, applicable error code is output to digital BCD display (P00040 \sim P0004F).

Program

Program example using I/O Parameter.

6. Programming

6.4. Application program examples



6.4. Application program examples

L27 L28	*1X0.0.1 _0002_0 *1X0.0.1 ACT	HO_ MOVE EN ENO -	Qa	vec 10 conversion valu	o of CH0 at %M000
129	DATA		8MWO 04	UES AND CONVENSION VALU	
130		GET_WORD REQ_DONE			
L31	0	BASE STAT			
L32	2	SLOT DATA	xmun Sav	/es error code %Ml01	
133	_F0002_ _C00	HADD			
L34					
L35	*1x0.0	.2 INT_TO_BCD _WORD EN EN0 -			
L36	%HW1	IN OUT *Q	w0.0.2 Col	rverts data saved in	%MW1 to BCD and
137			out	outs at %QW0.2.0	

6. Programming 6.4. Application program examples

7. Troubleshooting

7.1 Error codes

Errors which occur when A/D conversion module's RUN LED blinks are as described in Table 7.

Error Code	Description	RUN LED	
(Dec)	Description	status	
10	Module error (ASIC Reset Error).		
11	Module error (ASIC RAM or Register Error).	Flickers every	
20	Module error (A/D Conversion Error).	0.2s.	
30	Module error (EEPROM Error).		
40#	Module error (Offset value with the range of $1 \sim 5V$ or $4 \sim 20$ mA is set greater than or equal to Gain value.)		
41#	Module error (Offset value with the range of $0 \sim 5V$ or $0 \sim 20$ mA is set greater than or equal to Gain value.)		
42#	Module error (Offset value with the range of $0 \sim 10V$ is set greater than or equal to Gain value.)		
43#	Module error (Offset value with the range of $-10 \sim 10V$ is set greater than or equal to Gain value.)	Flickers every 1s.	
50#	Filter constant setting range exceeded.		
60#	Time average setting range exceeded.		
70#	Count average setting range exceeded.		
80#	Analog input range setting error (only for 2MLF-AC8A).		

Table 7 – List of error codes

7. Troubleshooting 7.1. Error codes

ň **ATTENTION**

- 1. # of the error code stands for the channel with error found.
- If two or more errors occur, the module saves only the first error code. 2.
- When the error is found and corrected, use the 'flag to request error clear'. For more information, refer Error Clear request Flag (UXY.11.0, X: Base No., Y: Slot No); or restart the unit. This stops the blinking LED and has the unit ready to detect the next error code. 3.

7. Troubleshooting 7.2. Troubleshooting

7.2 Troubleshooting

RUN LED blinks



(Dec)	Error Details	Action
40#		
41#	Modulo Offsot/Gain orror	Turn the power ON/OFF. If the error recurs, it is
42#		nearest Honeywell agency or branch office.
43#		
50#	Filter constant setting range exceeded	Change filter constant setting value within 1 ~ 99.
60#	Time average setting range exceeded	Change time average setting value within 4 ~ 16000.
70#	Frequency average setting range exceeded	Change frequency average setting value within 2 ~ 64000.
80#	Analog input range error (Only 2MLF-AC8A)	Refer to Address 1- input Voltage/Current section and then change the analog input range.
200	Analog Input Module 2M	II F-AV/8A AC8A Liser's Guide 131

7. Troubleshooting

7.2. Troubleshooting

RUN LED is OFF





CPU module cannot read A/D conversion value

Mismatch between analog input value and digital output value



7. Troubleshooting

7.2. Troubleshooting

H/W error of A/D conversion module

Turn the module Power OFF and ON. If the error recurs, it is likely to be a module defect. Contact the nearest Honeywell office or authorized service engineer.

Status check of A/D conversion module using System Monitor menu

Module type, module information, O/S version, and module status of A/D conversion module can be checked through SoftMaster system monitoring function. For more details, refer to Section 4.3.

8. Appendix

8.1 Appendix 1: Terminology

Terms and abbreviation used in the user's guide and the analog module in general are as described below.

A/D Converter	Converts analog input signal (voltage or current) to a proportional digital output value (raw count).
Analog Input Module	The module that converts analog voltage/current input signal to proportional digital value. It has a resolution of 14 and 16 bits depending on the converter used.
Channel	The inputs to A/D converters are connected through channels. Each voltage or current input is on a different channel. Every analog input module will have many channels (typically $8 \sim 16$). Thus, channel represents the circuitry used to connect input or output to an A/D or (D/A) converter.
Conversion time	Time taken by analog input module to sample and convert the analog input signal (one channel) into digital output value. Similarly, this term is also used to indicate the time required for analog output module to convert the digital value into an analog output signal.
D/A converter	Converts digital value to a proportional analog output signal (voltage or current, respectively).
Full Scale	The maximum value of the analog input (voltage or current) that can be converted by an A/D.
Full Scale Error	Difference between expected analog-converted value (voltage or current) and actual analog-converted value.
Full Scale Range	Difference between the maximum and the minimum value of the analog input (voltage or current).
LSB (Least Significant Bit)	The bit unit that gives minimum value (used in digital representation).

8. Appendix 8.1. Appendix 1: Terminology

Linearity Error	Analog I/O is related to continuous voltage/current value and digital value. The acceptable I/O value is defined as a line within a distance of the minimum 1LSB of voltage/current. I/O linearity error is regarded as the deviation between the acceptable-converted value and the actual-converted value on the graph. See the following figure.			
	Actual-converted value Acceptable-converted value			
Multiplexer	A switching circuit where many signals share one A/D converter or D/A converter.			
Analog Output Module	A module with output circuit to convert digital value from the process to analog output (voltage/current).			
Resolution	The minimum value recognizable by a measuring instrument, which is usually displayed in the engineering unit (1mV) or the number of bits. So when there are 14 bits, 16383 output values can be generated.			
Filter	Filters are used to avoid sudden changes in the digital value output caused either by external noise or sudden change in the analog input signal. Two types of filters used are: S/W and H/W filters.			

8. Appendix 8.1. Appendix 1: Terminology

Accuracy	Displays the maximum deviation between acceptable value and output value (voltage or current) for the full range of output. It also indicates the maximum deviation between acceptable value and digitally-converted input signal value for the full range of input. Generally, accuracy is displayed as percentage of the full scale value. Gain, offset, and linearity errors are all listed in the error codes generated.
Output accuracy	The difference between the actual analog output voltage/current value and the acceptable-converted value is indicated as percentage of full scale. It takes into account the effect of temperature, offset, gain, and drift error factors.

8.2 Appendix 2: External dimensions

External dimensions of 2MLF-AV8A/AC8A





8. Appendix 8.2. Appendix 2: External dimensions

Honeywell

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